

Vibro-Acoustic modelling, simulation and optimisation of anisotropic cellular materials



ROYAL INSTITUTE
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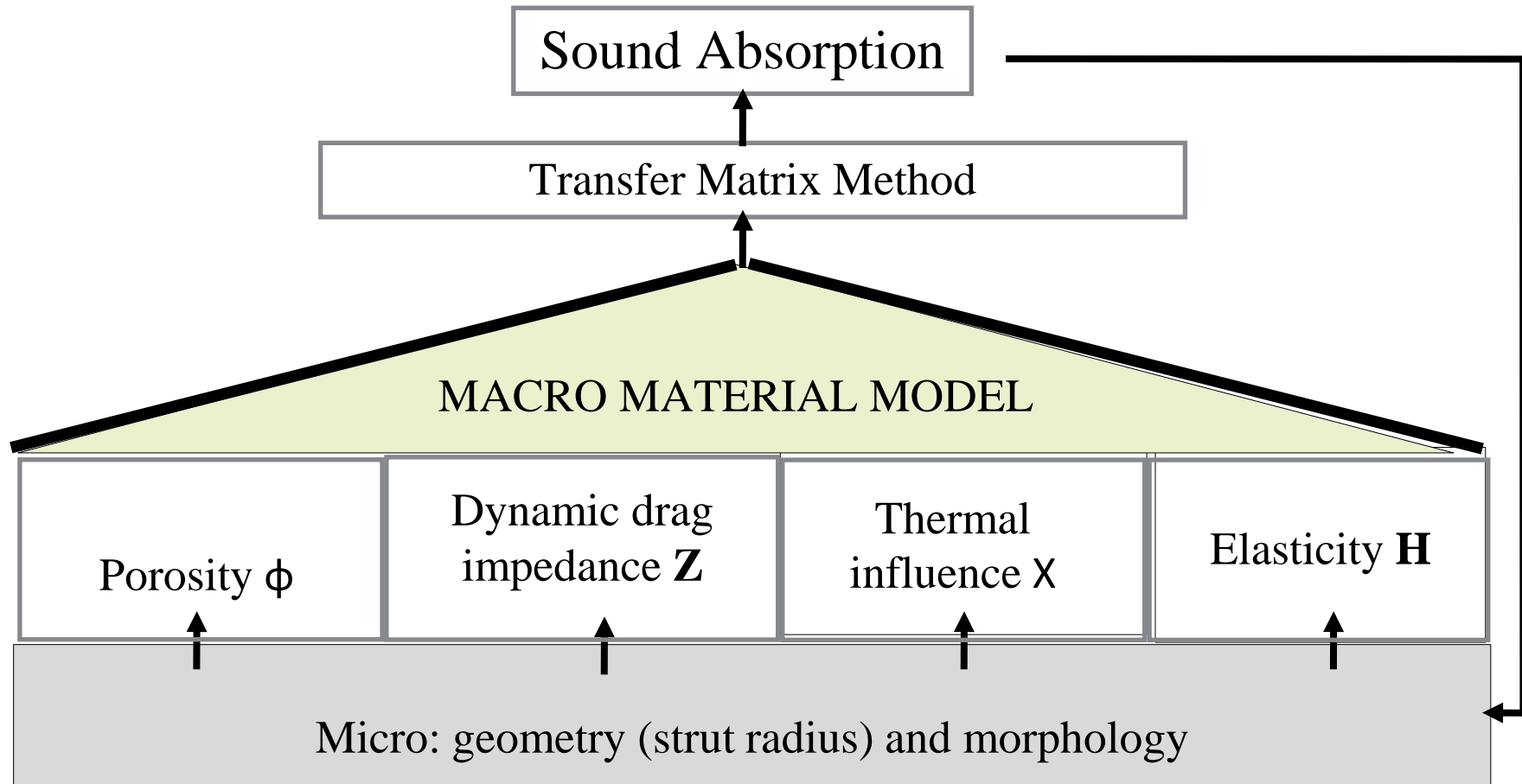
**with gratitude for all the collaborations over the years from
Olivier Dazel, Jacques Cuenca, Juan Pablo Parra Martinez, ...**

Sorrento

SAPEM' 23

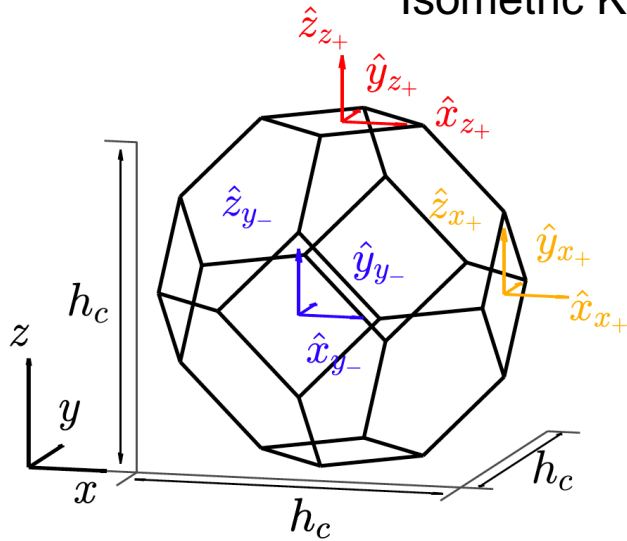
常熟

From microstructure to optimisation of macro performance

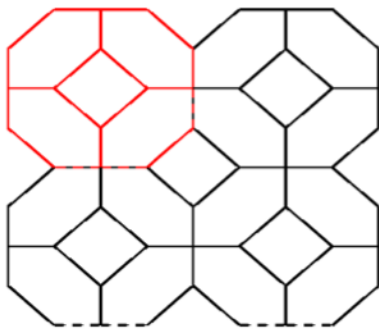


Geometry and morphology

Isometric Kelvin cell



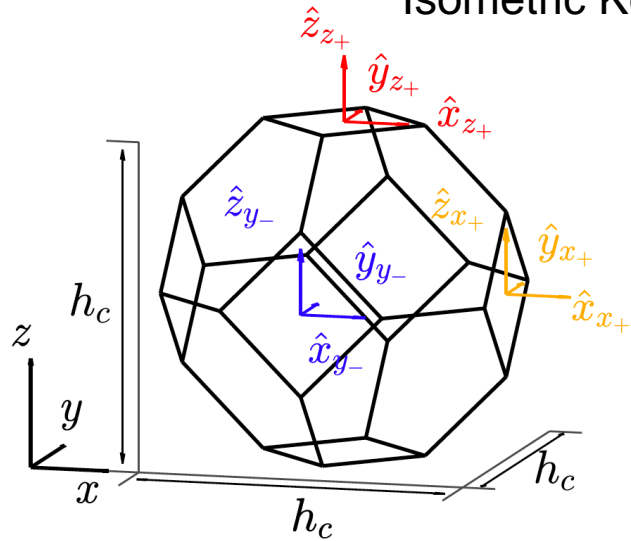
Iso



Cell arrays 2 x 2 x 2 - top view

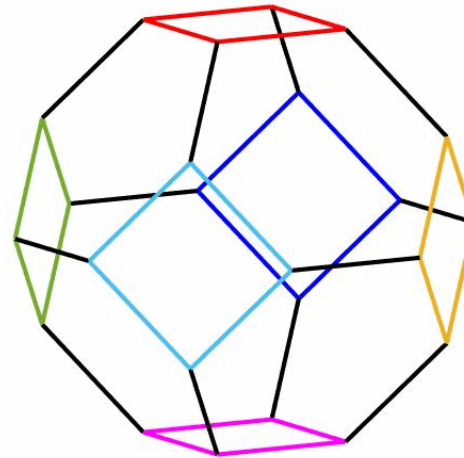
Geometry and morphology

Isometric Kelvin cell



0°

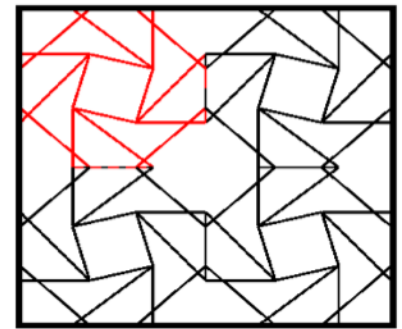
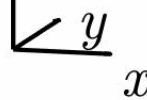
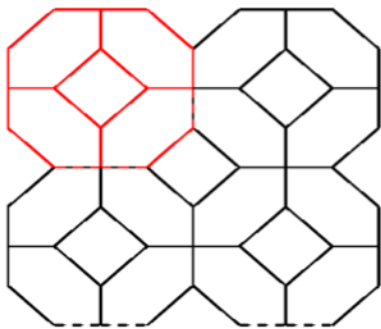
"Do the twist again"



Anti-symmetric

60°

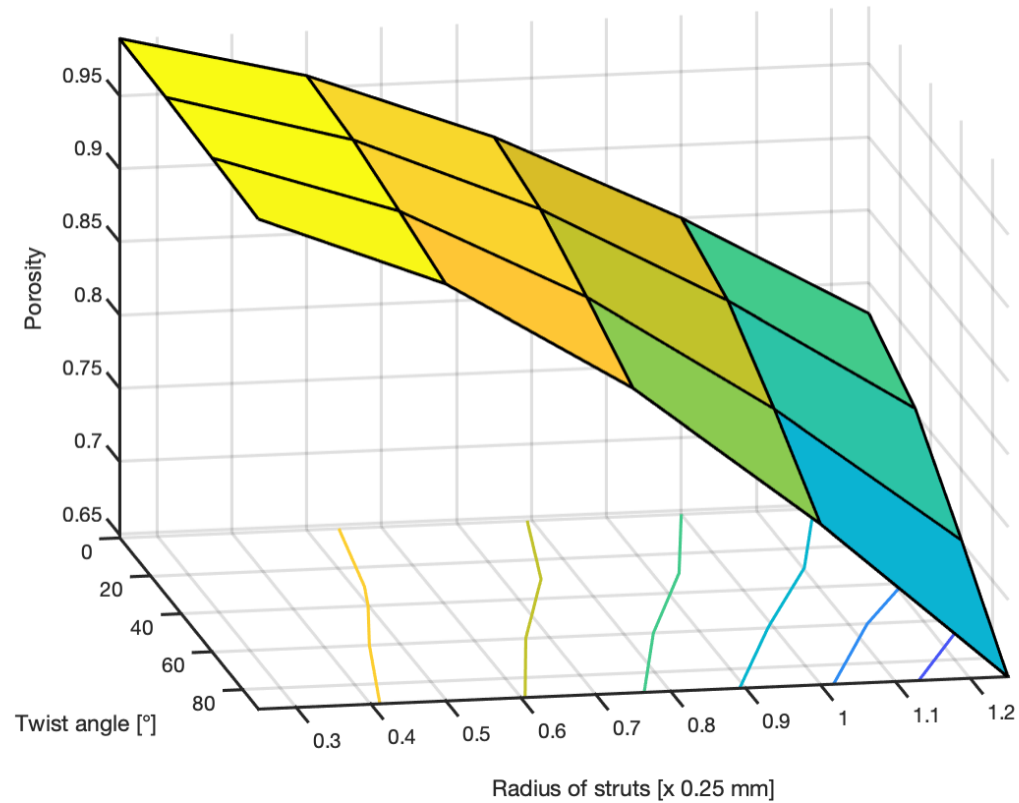
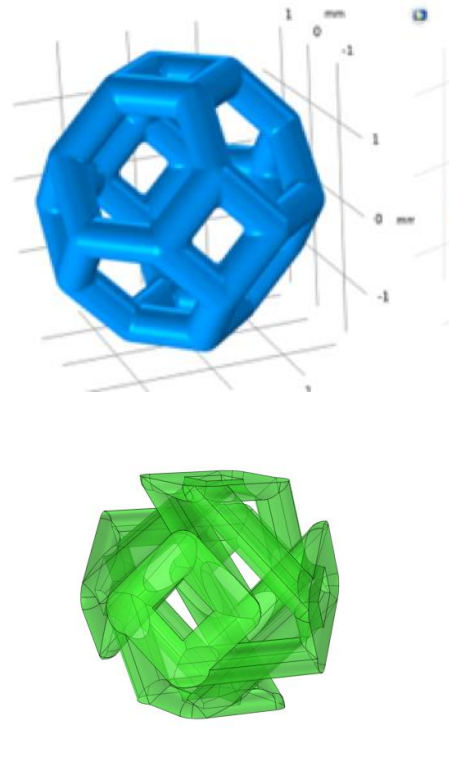
Iso



Cell arrays 2 x 2 x 2 - top view

Porosity

$$\phi = 1 - \frac{Volume_{struts}}{Volume_{cell}}$$



Thinner struts

Thicker struts

Governing equations

$$\mathbf{u}^t = (1 - \phi)\mathbf{u}^s + \phi\mathbf{u}^f$$

$$\nabla \hat{\boldsymbol{\sigma}}^s = -\omega^2 \tilde{\boldsymbol{\rho}}_s \mathbf{u}^s - \omega^2 \tilde{\boldsymbol{\tau}} \mathbf{u}^t$$

$$-\nabla p = -\omega^2 \tilde{\boldsymbol{\tau}} \mathbf{u}^s - \omega^2 \tilde{\boldsymbol{\rho}}_t \mathbf{u}^t$$

$$p = -\tilde{K}_{eq} \nabla \cdot \mathbf{u}^t$$

$$\hat{\boldsymbol{\sigma}}^s = \mathbf{H} \boldsymbol{\epsilon}^s$$

$$\tilde{\boldsymbol{\rho}}_s = (1 - \phi)\rho_s \mathbf{I} + \frac{(1 - \phi)^2}{\phi} \rho_f \mathbf{I} - \frac{i\mathbf{Z}}{\omega\phi^2}$$

Need to establish models for:

\mathbf{Z}

\tilde{K}_{eq}

\mathbf{H}

$$\tilde{\boldsymbol{\tau}} = -\frac{(1 - \phi)}{\phi} \rho_f \mathbf{I} + \frac{i\mathbf{Z}}{\omega\phi^2}, \quad \text{Cmf } \tilde{\boldsymbol{\rho}}_{eq} \tilde{\boldsymbol{\gamma}}$$

$$\tilde{\boldsymbol{\rho}}_t = \frac{\rho_f \mathbf{I}}{\phi} - \frac{i\mathbf{Z}}{\phi^2 \omega}. \quad \text{Cmf } \tilde{\boldsymbol{\rho}}_{eq}$$

- \mathbf{u}^s solid displacement
- \mathbf{u}^f fluid displacement
- p pressure
- K_{eq} fluid compressibility
- ρ_s solid constituent density
- ρ_f fluid density
- $\boldsymbol{\sigma}^s$ Cauchy stress
- \mathbf{H} Hooke's matrix
- $\boldsymbol{\epsilon}^s$ linear strain

Hooke's tensor linear elasticity - recap

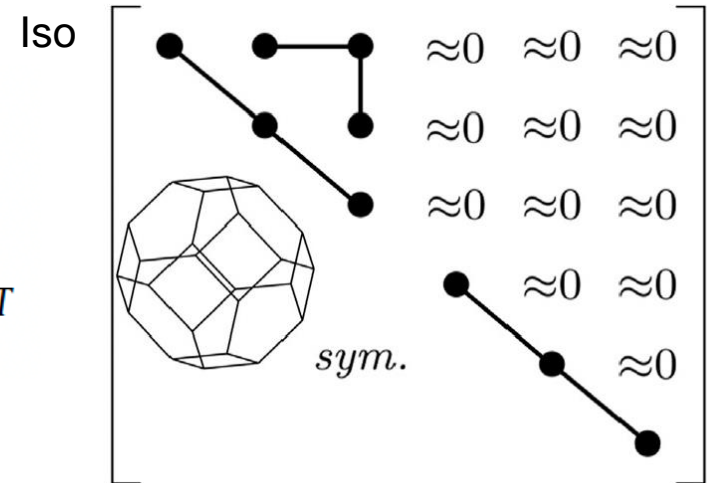
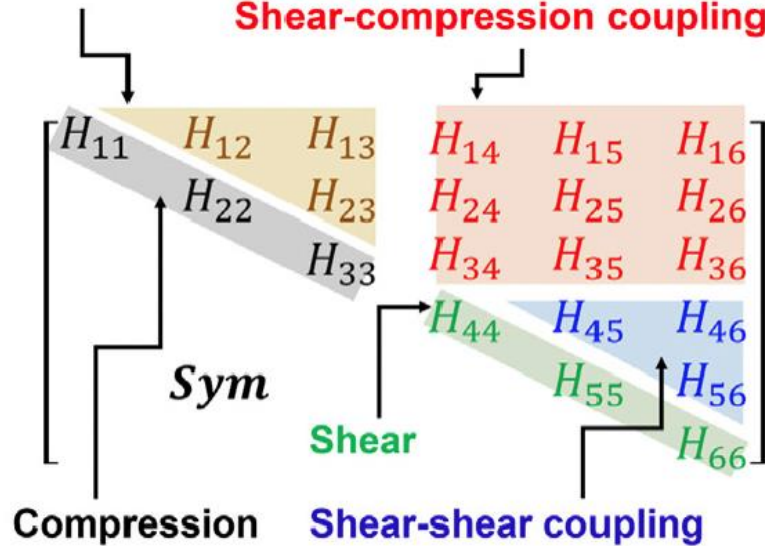
Hooke's law $\boldsymbol{\sigma} = \mathbf{H}\boldsymbol{\varepsilon}$

Cauchy stress $\boldsymbol{\sigma} = \{\sigma_{11}, \sigma_{22}, \sigma_{33}, \sigma_{12}, \sigma_{13}, \sigma_{23}\}^T$

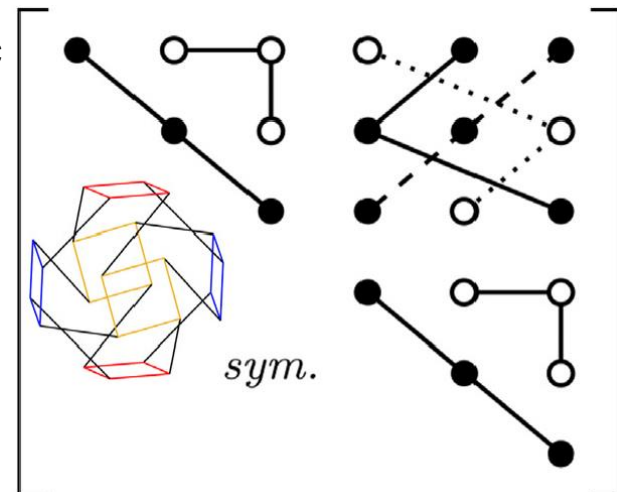
Linear strain $\boldsymbol{\varepsilon} = \{\varepsilon_{11}, \varepsilon_{22}, \varepsilon_{33}, 2\varepsilon_{12}, 2\varepsilon_{13}, 2\varepsilon_{23}\}^T$

Compression-compression coupling

Shear-compression coupling



Anti-symmetric twist

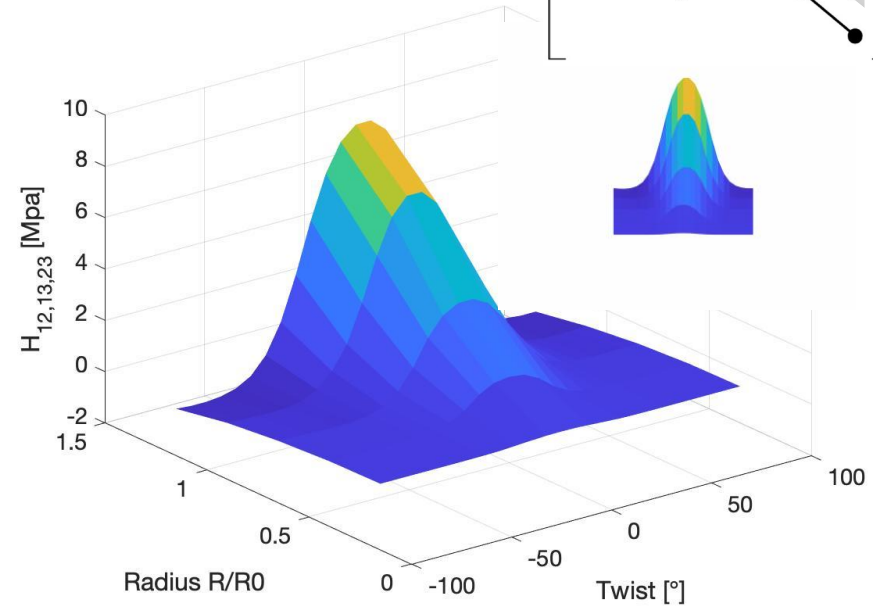
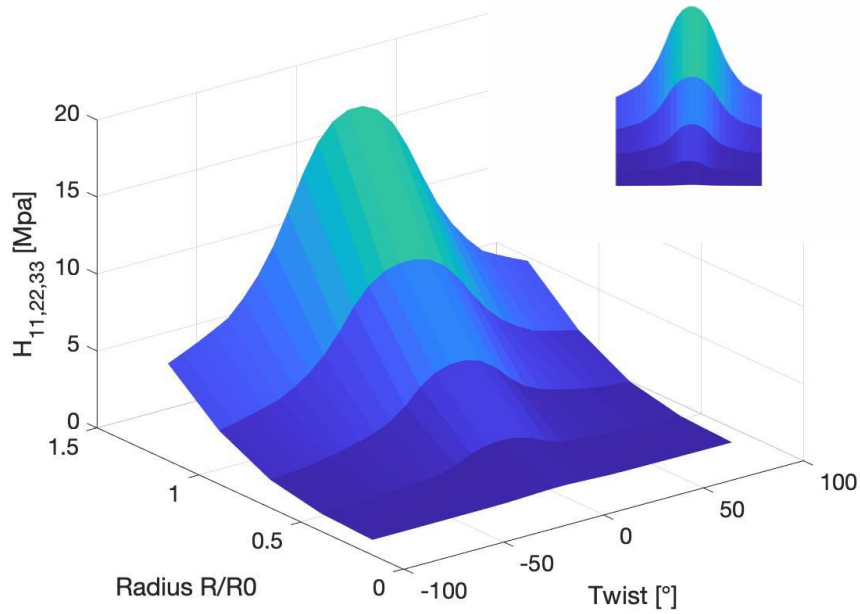
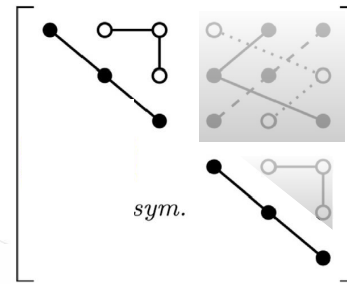


H. Mao et al, Twist, tilt and stretch: From isometric Kelvin cells to anisotropic cellular materials, Mater. Des. 193 (2020) 108855⁷

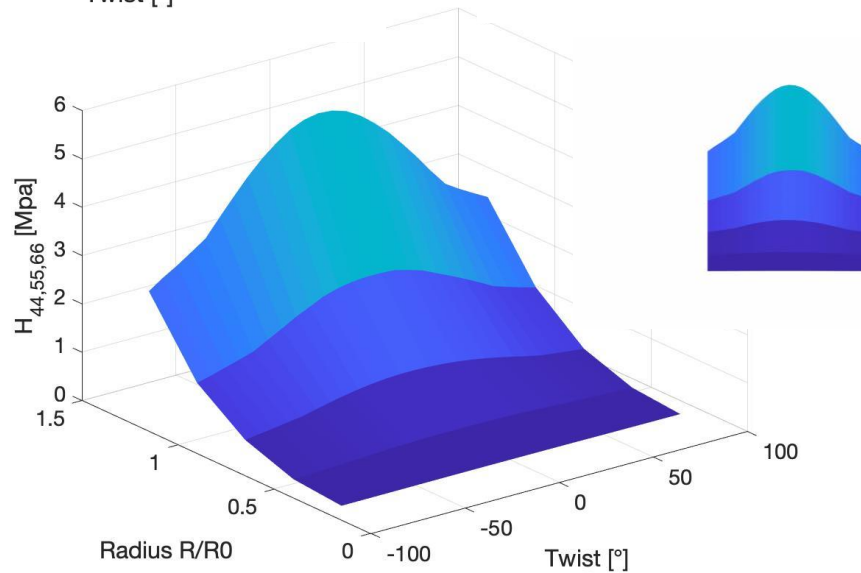
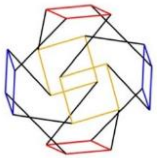
H. Mao, R. Rumlper, P. Göransson, An inverse method for characterisation of the static elastic Hooke's tensors of solid frame of anisotropic open-cell materials, Int. J. Engrg. Sci. 147 (2020) 103198



Hooke's tensor variation compression and shear moduli



Anti-symmetric twist

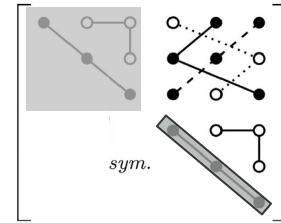


$R_0 = 0.25$ mm

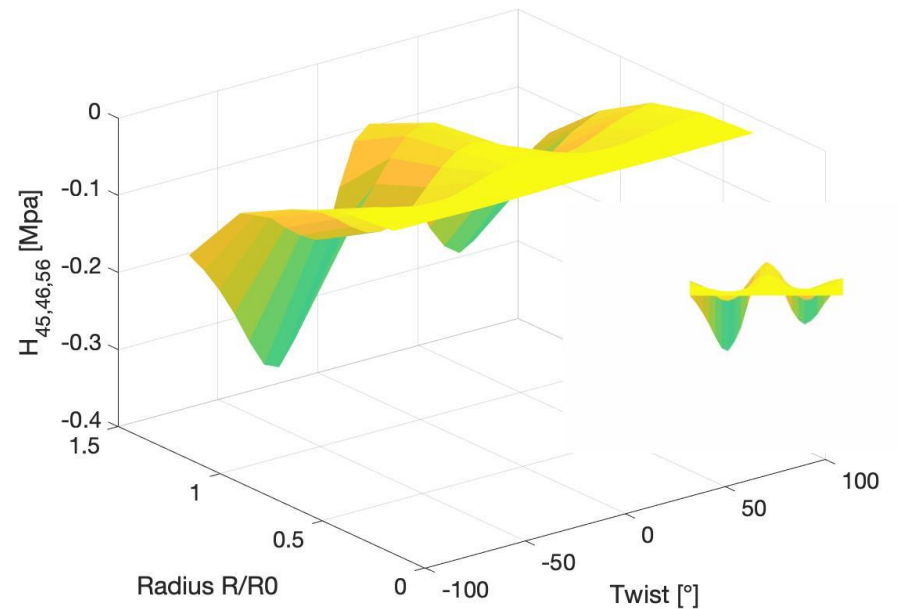
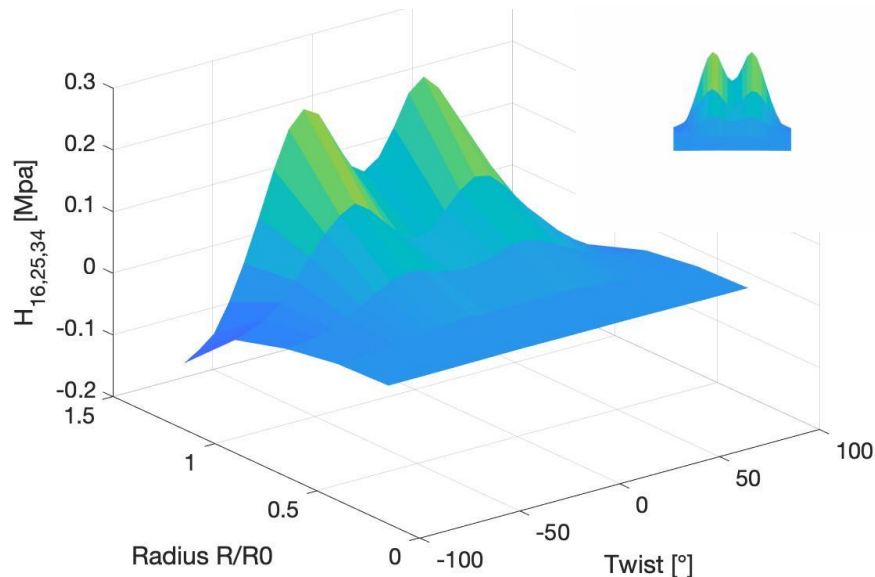
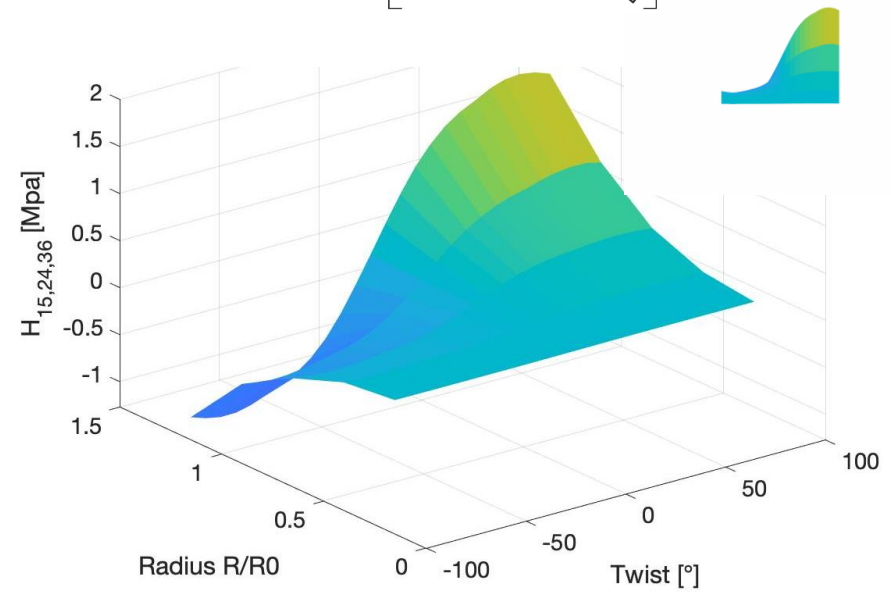
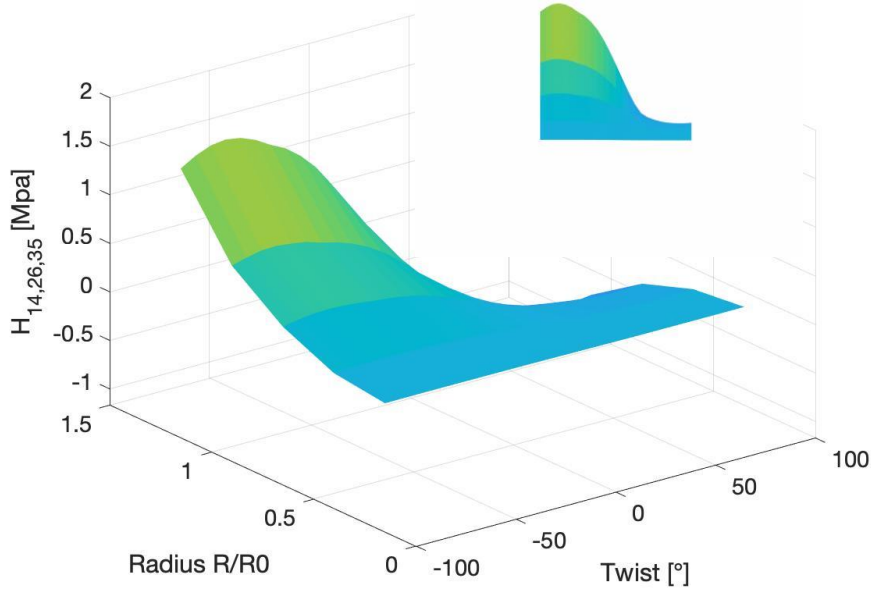




Hooke's tensor variation compression-shear & shear-shear

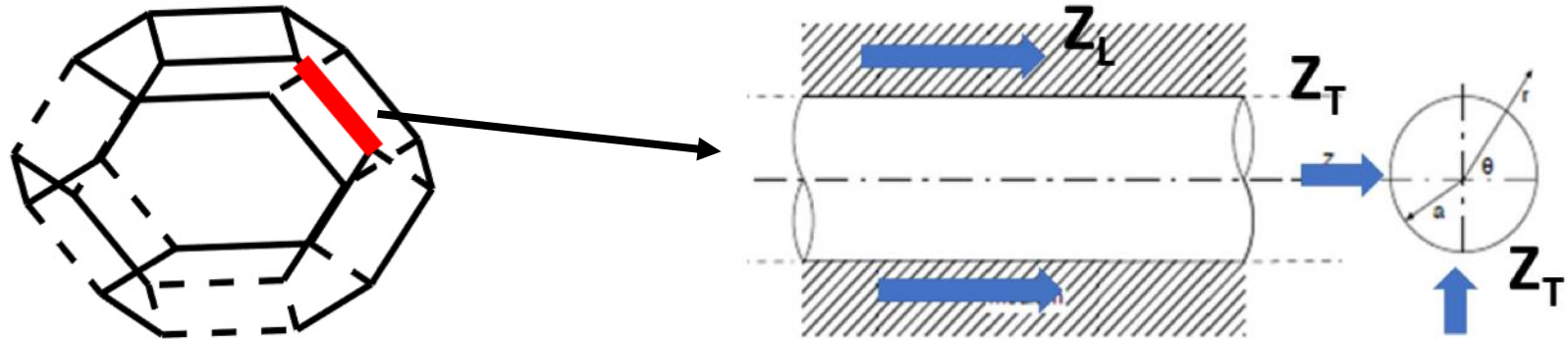


R0=0.25 mm



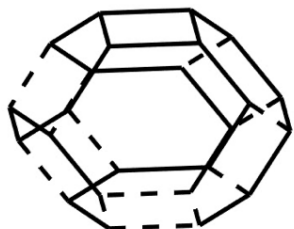
Dynamic drag impedence

In a local coordinate system

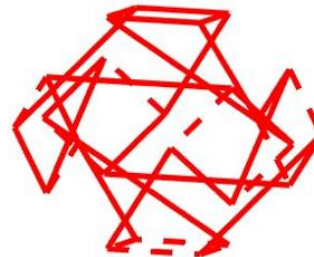


$$\mathbf{Z}_{\text{cell}} = \begin{bmatrix} Z_{11} & Z_{12} & Z_{13} \\ Z_{21} & Z_{22} & Z_{23} \\ Z_{31} & Z_{32} & Z_{33} \end{bmatrix} = \frac{1 - \phi}{V_s} \sum_{n=1}^N \mathbf{R}_n \begin{bmatrix} Z_{L_n} & 0 & 0 \\ 0 & Z_{T_n} & 0 \\ 0 & 0 & Z_{T_n} \end{bmatrix} \mathbf{R}_n^T.$$

\mathbf{R}_n
rotation matrix



$$\begin{pmatrix} Z_{iso} & 0 & 0 \\ 0 & Z_{iso} & 0 \\ 0 & 0 & Z_{iso} \end{pmatrix}$$

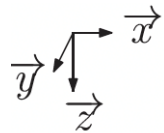


$$\begin{bmatrix} Z_{11} & Z_{12} & Z_{13} \\ Z_{21} & Z_{22} & Z_{23} \\ Z_{31} & Z_{32} & Z_{33} \end{bmatrix}$$

Solving for the absorption

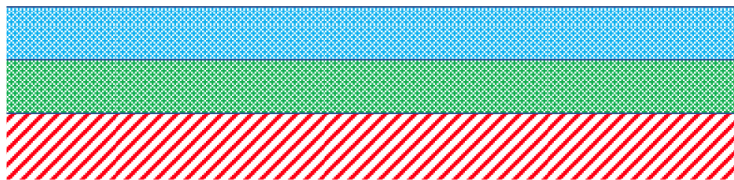
Assume a semi-infinite stack of two layers on a rigid backing, total thickness 50 mm.

Each of the layers is a (possibly) twisted Kelvin cell based equivalent material.



Initially same thickness

Layer 1
Layer 2

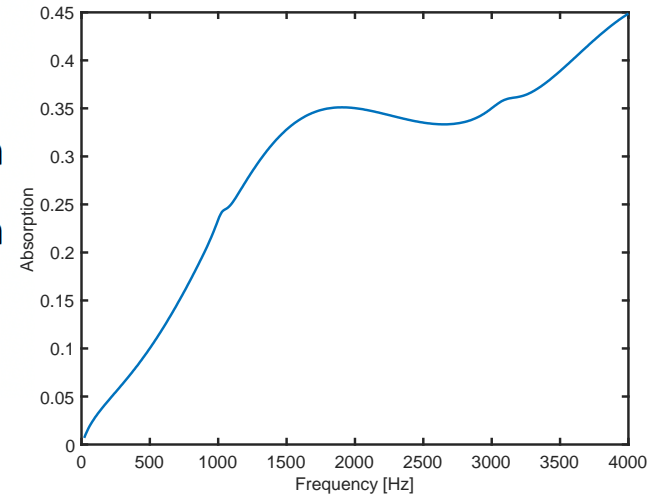


Rigid backing

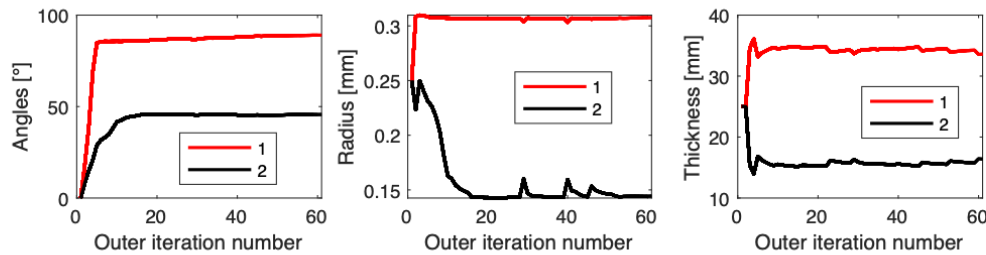
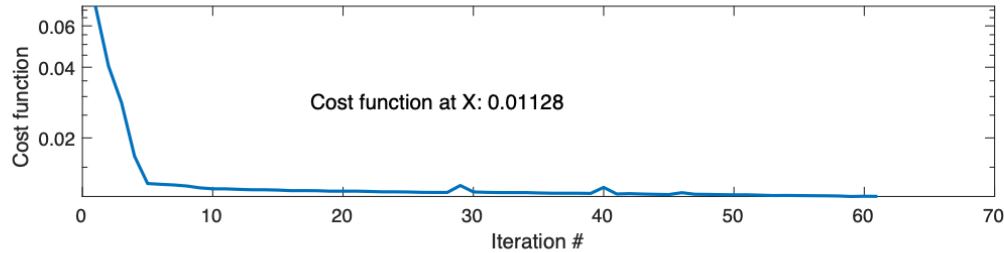
25 mm
25 mm

$R_0 = 0.25 \text{ mm}$

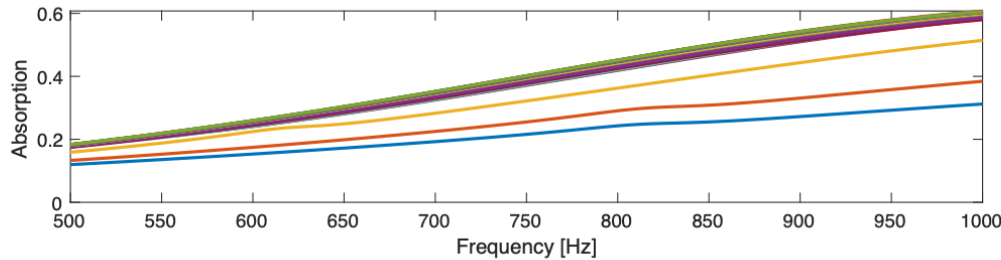
$\phi = 0.85$



Two layers - cost function max(Absorption) 500-1000 Hz



NB 4 design variables, radii and thicknesses

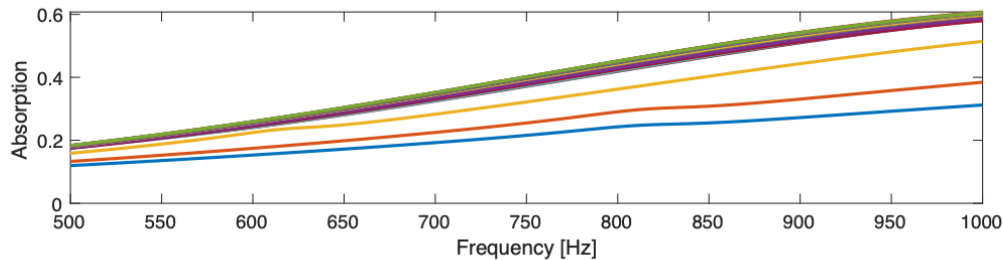
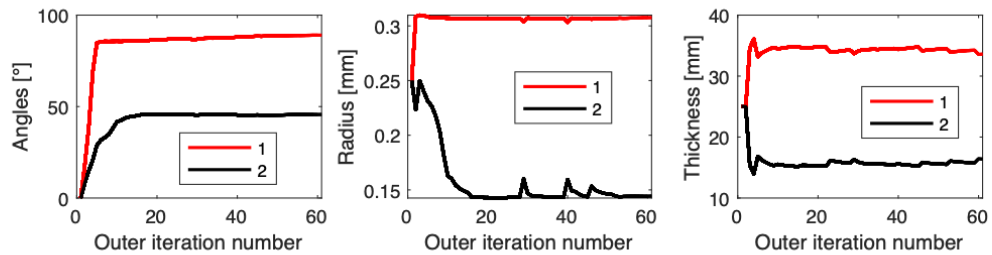
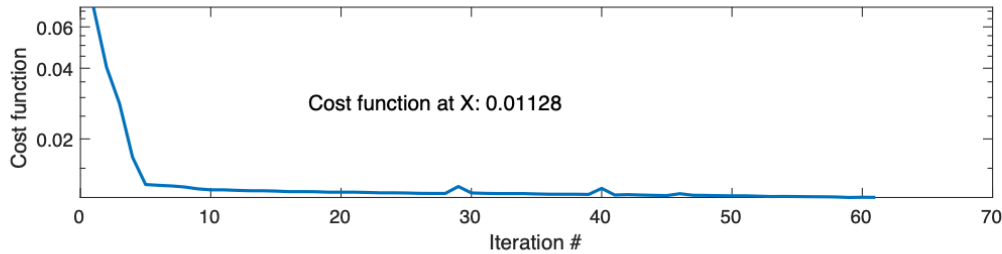


Final solution

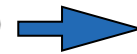
Initial solution

Optimisation step

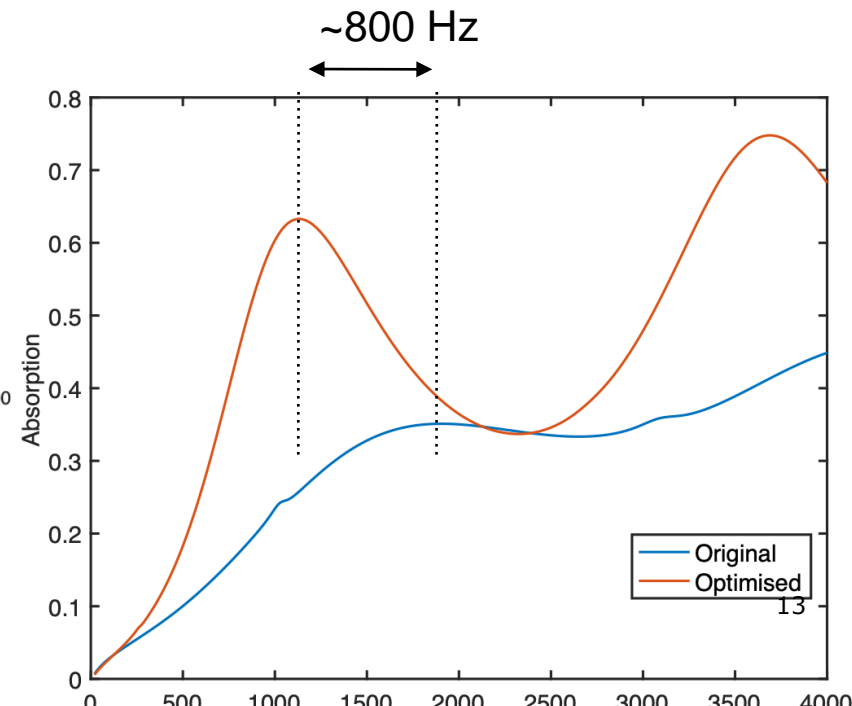
Two layers - cost function max(Absorption) 500-1000 Hz



Optimisation step



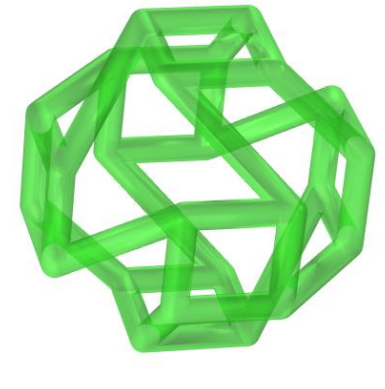
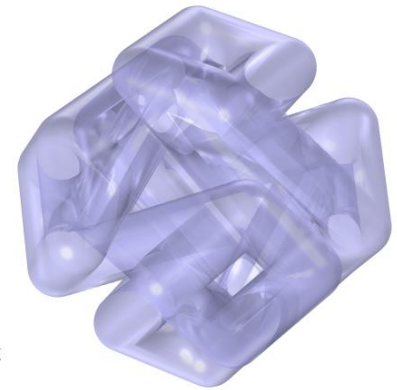
Absorption spectrum



Two layers solution- max(Absorption) 500-1000 Hz

Layer	Twist °	Radius mm	Thickness mm	Porosity %	Surface density kg/m ²
top	89	0.31	34	66	18.4
bottom	46	0.14	16	93	1.8

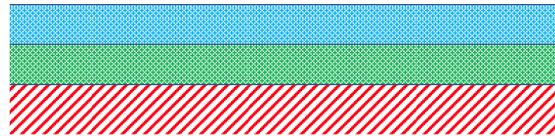
Optimal cell
microgeometries



Optimised anisotropic

36 mm

14 mm



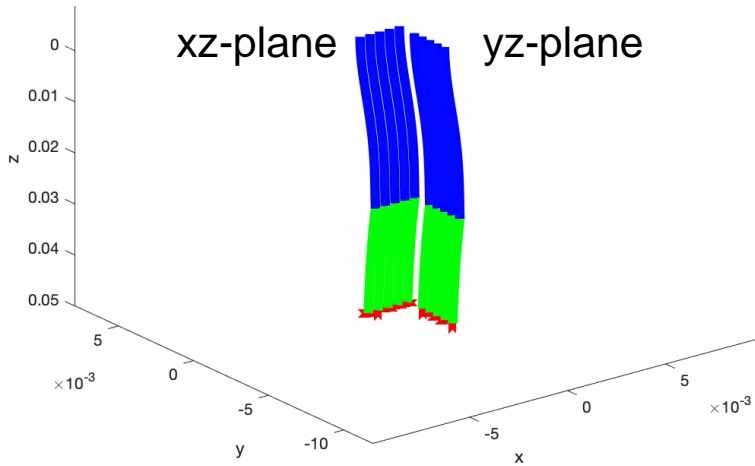
25 mm

25 mm

Iso

Rigid backing

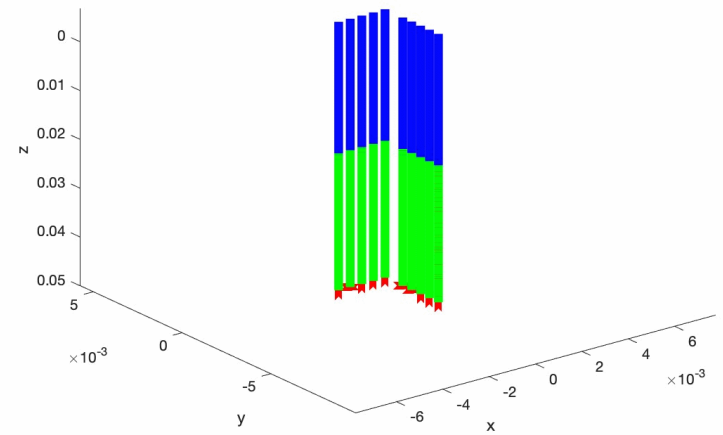
Displacement field at $\omega t = 0^\circ$



~1100 Hz

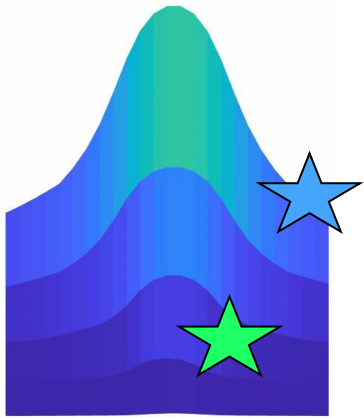
$U = \text{real}(u * e^{i(\omega t)})$, animation over $\omega t \in [0, 2\pi]$

Displacement field at $\omega t = 0^\circ$



~1900 Hz

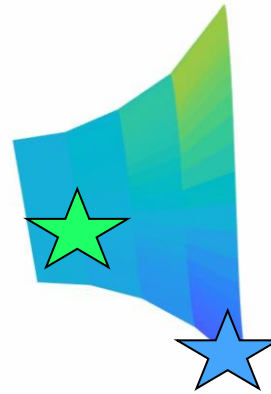
The optimal solutions elastic parameters



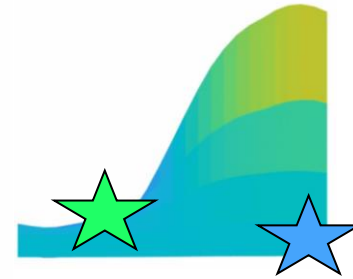
H11



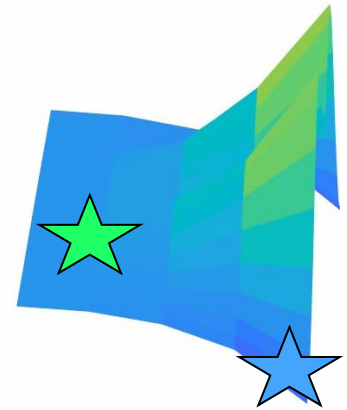
H12



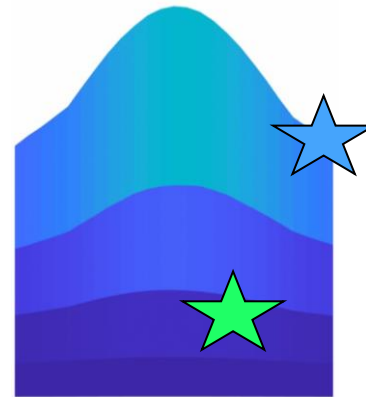
H14



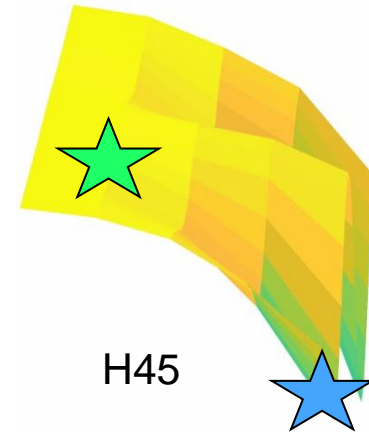
H15



H16



H44

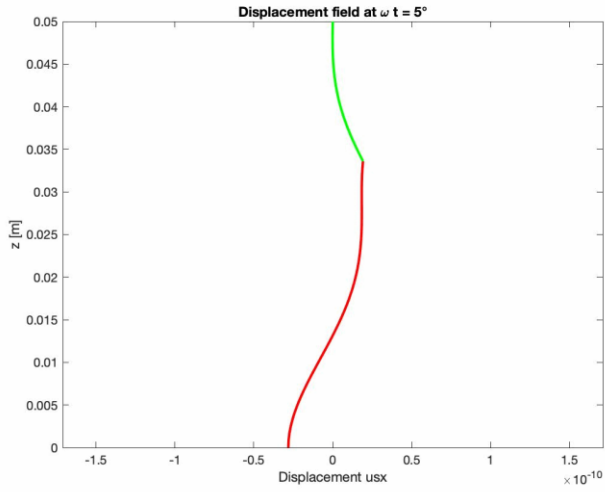


H45

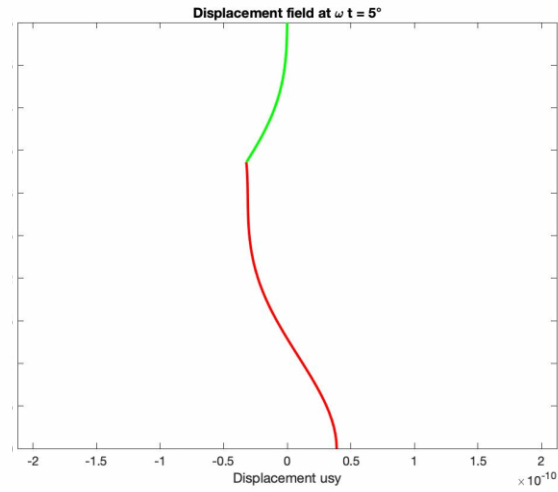
Conclusions

- General framework for acoustic anisotropic poro-elastic material modelling based on an open cell template.
 - Microstructure geometry based modelling of elasticity and viscous drag enable meaningful optimisation.
 - Optimal vibro-acoustic performance:
 - Resulting cell geometry highly distorted and different between layers
 - A complex interplay between different deformation mechanisms
-

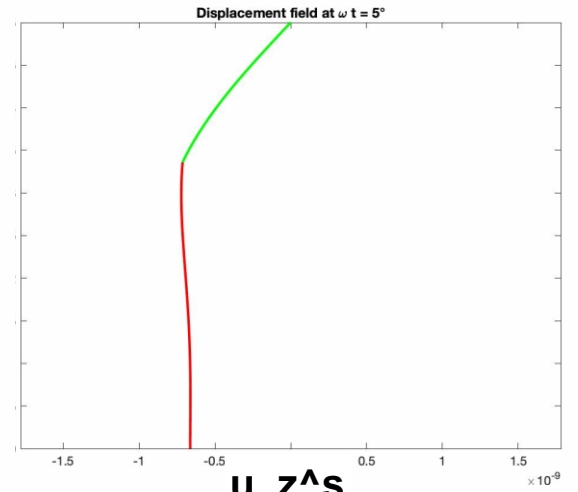
Aniso optimal @ absorption peak 1100 Hz



u_x^s



u_y^s

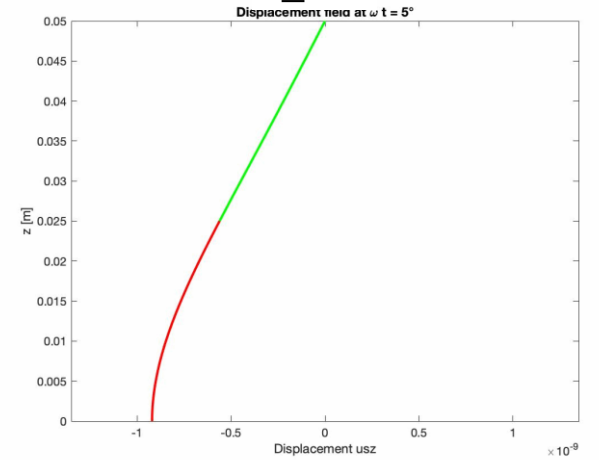


u_z^s

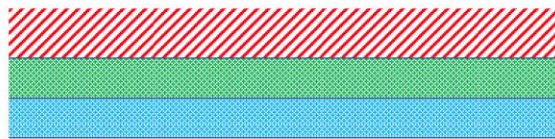
Iso @ absorption peak 1800 Hz

0

0

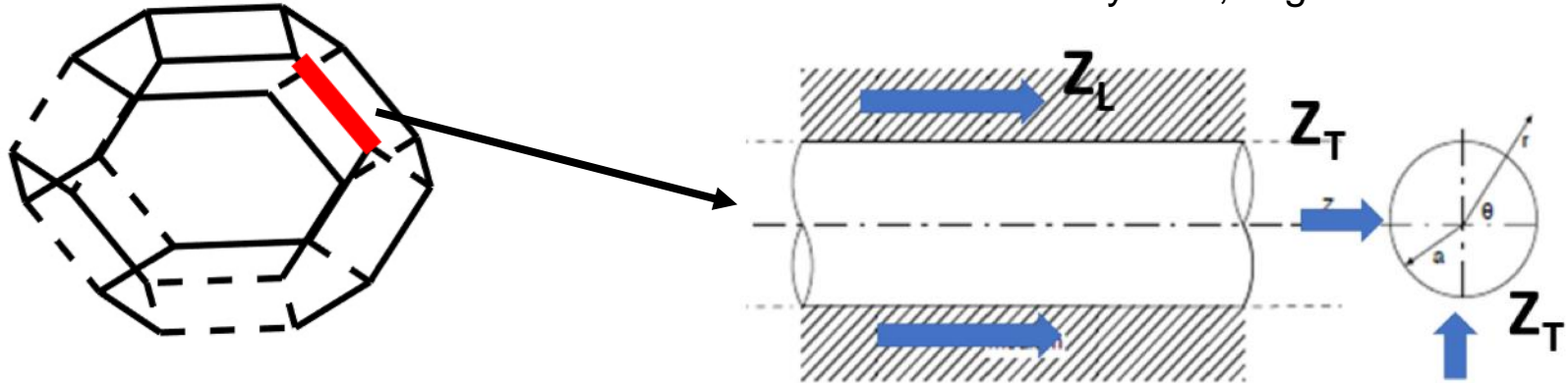


Rigid backing



Dynamic drag impedence

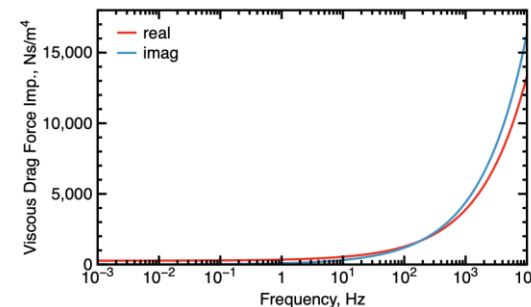
In a local coordinate system, aligned with the strut



$$Z_{Ln} = 2\pi \int_0^{l_n} r_n k_\beta \mu_f \frac{H_1^{(2)}(k_\beta r_n)}{H_0^{(2)}(k_\beta r_n)} dz = 2\pi r_n l_n k_\beta \mu_f \frac{H_1^{(2)}(k_\beta r_n)}{H_0^{(2)}(k_\beta r_n)},$$

$$Z_{Tn} = i\pi r_n^2 l_n \rho_f \omega \left(1 - \frac{4H_1^{(2)}(k_\beta r_n)}{k_\beta r_n H_0^{(2)}(k_\beta r_n)} \right),$$

$$k_\beta = \sqrt{-(i\omega\rho_f/\mu_f)}$$



Hooke's matrix

Normalised with H_{11}

Layer 1 x 5.5 MPa = H_{11}

			ϵ_{xy}	ϵ_{xz}	ϵ_{yz}
1.0000	-0.1320	-0.1320	-0.1995	0.2507	-0.0189
-0.1320	1.0000	-0.1320	0.2507	-0.0189	-0.1995
-0.1320	-0.1320	1.0000	-0.0189	-0.1995	0.2507
-0.1995	0.2507	-0.0189	0.4663	-0.0216	-0.0216
0.2507	-0.0189	-0.1995	-0.0216	0.4663	-0.0216
-0.0189	-0.1995	0.2507	-0.0216	-0.0216	0.4663

Layer 2 x 0.9 MPa = H_{11}

1.0000	0.0126	0.0126	-0.1132	0.1451	0.0175
0.0126	1.0000	0.0126	0.1451	0.0175	-0.1132
0.0126	0.0126	1.0000	0.0175	-0.1132	0.1451
-0.1132	0.1451	0.0175	0.3750	-0.0323	-0.0323
0.1451	0.0175	-0.1132	-0.0323	0.3750	-0.0323
0.0175	-0.1132	0.1451	-0.0323	-0.0323	0.3750