On pulse propagation in poro-visco-elastic felt-like material

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Motivation



Figure: SEM images¹ of a) wool felt, b) polypropylene felt and c) carbon felt.

- Felt is a non-woven fabric (composite material) produced by wet felting natural or synthetic fibres
- Felt properties are less understood than the properties of the fibers within them
- Strain wave propagation, dispersion and dissipation through felts
- Wide range of applications

¹J. S. Winzer, *Production and Characterisation of Alumina-Copper Interpenetrating Composites*, VVB Laufersweiler Verlag, Darmstadt, Germany, 2013.

Experimental studies of wool felt and piano hammers²



Piano hammer collision dynamics: Static and dynamic testing of **piano** hammers and **felt pads**. Characterising and measuring of properties of wool felt.



²A. Stulov, A. Mägi, "Piano hammer testing device," *Proc. Estonian Acad. Sci. Engin.*, **6**(4), pp. 259–267, 2000.

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Theoretical studies of wool felt and piano hammers^{3,4}



Figure: Typical hammer collisions lasting for t_c s. Experimental data (black) vs. fitted model data (blue).

$$F(t) = F_0 \left[w^p(t) - \frac{\gamma}{\tau} \int_0^t w^p(\xi) \exp\left(\frac{\xi - t}{\tau}\right) d\xi \right],$$
(1)

where γ is the hereditary amplitude, τ is the relaxation time, p is the compliance exponent, F_0 is the instantaneous stiffness.

³A. Stulov, "Hysteretic model of the grand piano hammer felt," *J. Acoust. Soc. Am.*, **97**(4), pp. 2577–2585, 1995.

⁴A. Stulov, "Dynamic behavior and mechanical features of wool felt," *Acta Mech.*, **169**, pp. 13–21, 2004.

Wool felt model

A hereditary visco-elastic continuum can't be described by the static Young's modulus E. Instead, the modulus is replaced by a time-dependant operator in the form $E[1 + \mathcal{R}(t)*]$ here

$$\mathcal{R}(t) = \frac{\gamma}{\tau_0} \exp\left(-\frac{t}{\tau_0}\right), \qquad 0 \leqslant \gamma < 1,$$
(2)

where γ is the hereditary amplitude and τ_0 is the relaxation time. **Constitutive relation** of the felt is proposed in the following form^{5,6}:

$$\sigma(\varepsilon) = E_{\rm d} \left[\varepsilon^p(t) - \mathcal{R}(t) * \varepsilon^p(t) \right] = E_{\rm d} \left[\varepsilon^p(t) - \frac{\gamma}{\tau_0} \int_0^t \varepsilon^p(\xi) \exp\left(\frac{\xi - t}{\tau_0}\right) \mathrm{d}\xi \right], \quad (3)$$

here E_{d} is the dynamic Young's modulus, p is the compliance exponent.

⁵D. Kartofelev, A. Stulov, "Propagation of deformation waves in wool felt," *Acta Mech*, **225**, pp. 3103–3113, 2014.

⁶D. Kartofelev, A. Stulov, "Wave propagation and dispersion in microstructured wool felt," *Wave Motion*, **57**, pp. 23–33, 2015.

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Analysis of constitutive relation (3)



Fast loading cycle, $t_{\rm c} \ll \tau_0$:

$$\sigma(\varepsilon) = E_{\rm d}\varepsilon^p(t), \qquad (4)$$

where $E_{\rm d}$ is the dynamic Young's modulus.

Slow loading cycle, $t_c \gg \tau_0$:

$$\sigma(\varepsilon) = E_{\rm s}\varepsilon^p(t), \tag{5}$$

where $E_{\rm s}=E_{\rm d}(1-\gamma)$ is the static Young's modulus.

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The felt model equation is derived from 1-D equation of motion

$$p\frac{\partial^2 u}{\partial t^2} = \frac{\partial\sigma}{\partial x},\tag{6}$$

where ρ is the density and u(x,t) is the displacement. Substitution of constitutive relation (3) into (6) and eliminating of the integral term leads to the following model equation:

$$\rho \frac{\partial^2 u}{\partial t^2} + \rho \tau_0 \frac{\partial^3 u}{\partial t^3} - E_{\rm d} \left\{ (1-\gamma) \frac{\partial}{\partial x} \left[\left(\frac{\partial u}{\partial x} \right)^p \right] + \tau_0 \frac{\partial^2}{\partial x \partial t} \left[\left(\frac{\partial u}{\partial x} \right)^p \right] \right\} = 0.$$
(7)

In the case of **wool felt** used in certain piano hammers, the values of physical material constants are: $E_{\rm s}=0.6$ MPa, $\rho=10^3$ kg/m³, $\gamma=0.95$, $\tau_0=10$ μ s, $1.0 . Dependent parameter values: <math>E_{\rm d}=15$ MPa, $c_{\rm s}=25$ m/s, $c_{\rm d}=125$ m/s.

Model equation: Dimensionless form

Dimensionless variables are introduced as follows:

$$u \leftarrow \frac{u}{L}, \qquad x \leftarrow \frac{x}{L}, \qquad t \leftarrow \frac{t}{T},$$
 (8)

where

$$T = \tau_0/\delta, \quad L = c_{\rm d}T\sqrt{\delta}, \quad \delta = 1 - \gamma, \quad c_{\rm d} = \sqrt{E_{\rm d}/\rho}, \quad c_{\rm s} = c_{\rm d}\sqrt{\delta}.$$
 (9)

Thus, the dimensionless form of model equation (7) in terms of strain variable $\varepsilon = \partial u / \partial x$ takes the form:

$$\varepsilon_{tt} = (\varepsilon^p)_{xx} + (\varepsilon^p)_{xxt} - \delta\varepsilon_{ttt},$$
(10)

where p is the material compliance exponent and $\delta \in (0, 1]$ is related to all hereditary and dissipative properties. If $\delta \to 0$, i.e., $\gamma \to 1$, then the hereditary properties approach maximum levels and the dissipative properties approach minimum levels.

In the case of physical constant values shown on previous slide:

L = 6.25 mm and T = 0.25 ms.

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Non-hysteretic model equations

The limit cases for rapid and slow material loading cycles.



Fast loading cycle, $t_c \ll \tau_0$:

$$\sigma(\varepsilon) = E_{\rm d}\varepsilon^p(t).$$

Model equation in dimensionless strain variable:

$$\varepsilon_{tt} = (\varepsilon^p)_{xx}.$$
 (11)

Slow loading cycle, $t_c \gg \tau_0$:

$$\sigma(\varepsilon) = E_{\rm s}\varepsilon^p(t).$$

Model equation in dimensionless strain variable:

$$\varepsilon_{tt} = \delta^2(\varepsilon^p)_{xx}.$$
 (12)

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Dispersion analysis of model equation

The solution to model equation (10) can be assumed in the form

$$\varepsilon(x,t) \propto e^{i(kx - \Omega t)}.$$
 (13)

The **characteristic equation** that corresponds to **linearised** model equation (10) has the following form:

$$k^2 - \Omega^2 - ik^2\Omega + i\delta\Omega^3 = 0.$$
(14)

In general case angular frequency $\Omega(k)$ is a complex quantity

$$\Omega(k) = \omega(k) + i\mu(k).$$
(15)

Assumed travelling wave solution (13) can be rewritten as follows:

$$\varepsilon(x,t) \propto e^{i[kx - \Omega(k)t]} \propto e^{ikx - i\omega(k)t + \mu(k)t} \propto e^{\mu(k)t} \cdot e^{i[kx - \omega(k)t]}.$$
 (16)

It is easy to see that $\mu(k)$ acts as an exponential dissipation coefficient. The spectral components decay exponentially as $t \to \infty$ for $\mu(k) < 0$.

Dispersion and dissipation relations

$$\begin{cases} \omega(k) = \frac{\sqrt{6}}{12\delta S} \sqrt{\sqrt[3]{2}S^4 - 4S^2(1 - 3k^2\delta) + 2\sqrt[3]{4}(1 - 3k^2\delta)^2}, \\ \mu(k) = \frac{1}{12\delta S} \left[\sqrt[3]{4}S^2 - 4S + 2\sqrt[3]{2}(1 - 3k^2\delta)\right], \end{cases}$$
(17)

where

$$S = \sqrt[3]{2 - 9k^2\delta(1 - 3\delta) + 3k\delta\sqrt{3Q}},$$
(18)

$$Q = 4k^4\delta - k^2(1 + 18\delta - 27\delta^2) + 4.$$
 (19)

Three distinct regimes of solutions exist depending on the value of δ :

- 0 < δ ≤ 1/9: High hereditary properties accompanied by a band gap (BG) and a region with negative group velocity (NGV)
- **2** $1/9 < \delta < 1$: Low hereditary properties with continuous and smooth curves
- **(3)** $\delta = 1$: Non-hereditary, dispersionless case

The region with NGV exists for $0<\delta \lesssim 0.134$ and a BG exists for $0<\delta < 1/9.$

Dispersion and dissipation curves for $\delta=0.05$

Case 1: High hereditary properties. Case corresponds best to wool felt because for wool felt $\gamma=0.95.$



Figure: Dispersion and dissipation curves and corresponding phase and group velocity curves. This case features both normal $(v_{\rm ph}(k) > v_{\rm gr}(k))$ and anomalous $(v_{\rm ph}(k) < v_{\rm gr}(k))$ dispersion types.

Dispersion and dissipation curves for $\delta = 1/9 \approx 0.11$

Case at the boundary that separates Case 1 from Case 2.



Figure: Dispersion and dissipation curves and corresponding phase and group velocity curves. This case features both normal $(v_{\rm ph}(k) > v_{\rm gr}(k))$ and anomalous $(v_{\rm ph}(k) < v_{\rm gr}(k))$ dispersion types.

Dispersion and dissipation curves for $\delta=0.2$

Case 2: Low hereditary properties



Figure: Dispersion and dissipation curves and corresponding phase and group velocity curves.

Initial value problem (IVP) applied to three models:

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where $\delta = 0.05$, p = 1.1, $\beta = 0.015$ is the pulse width parameter, the corresponding spectral component $k \approx 2$. Resulting phase speed is δ .



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Conclusions

- An equation for modelling strain wave propagation through felt and similar materials was presented.
- Dispersion and dissipation analysis was performed. Surprisingly, dispersion curves featured a region with NGV and a BG.
- Three distinct solution behaviour regimes were identified.
- A *naive interpretation* of dispersion relation may lead to wrong conclusions about the underlying model and physics.
- Despite being predicted by the dispersion analysis the BG and NGV may not influence the wave evolution. Wave lengths related to the NGV and BG spectral components were *too big* relatively speaking. If the material loading and unloading time-scale is *much too great* in comparison to material relaxation time τ_0 , then any imaginable effects will be negligibly small. Similar masking effect also influenced the dissipation.

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