

Dispersion relations of guided acoustic waves in poroelastic-based multilayer structures

Mathieu Maréchal

In collaboration with

Olivier Dazel, Alan Geslain, and Jean-Philippe Groby (LAUM)

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SAPEM 2023

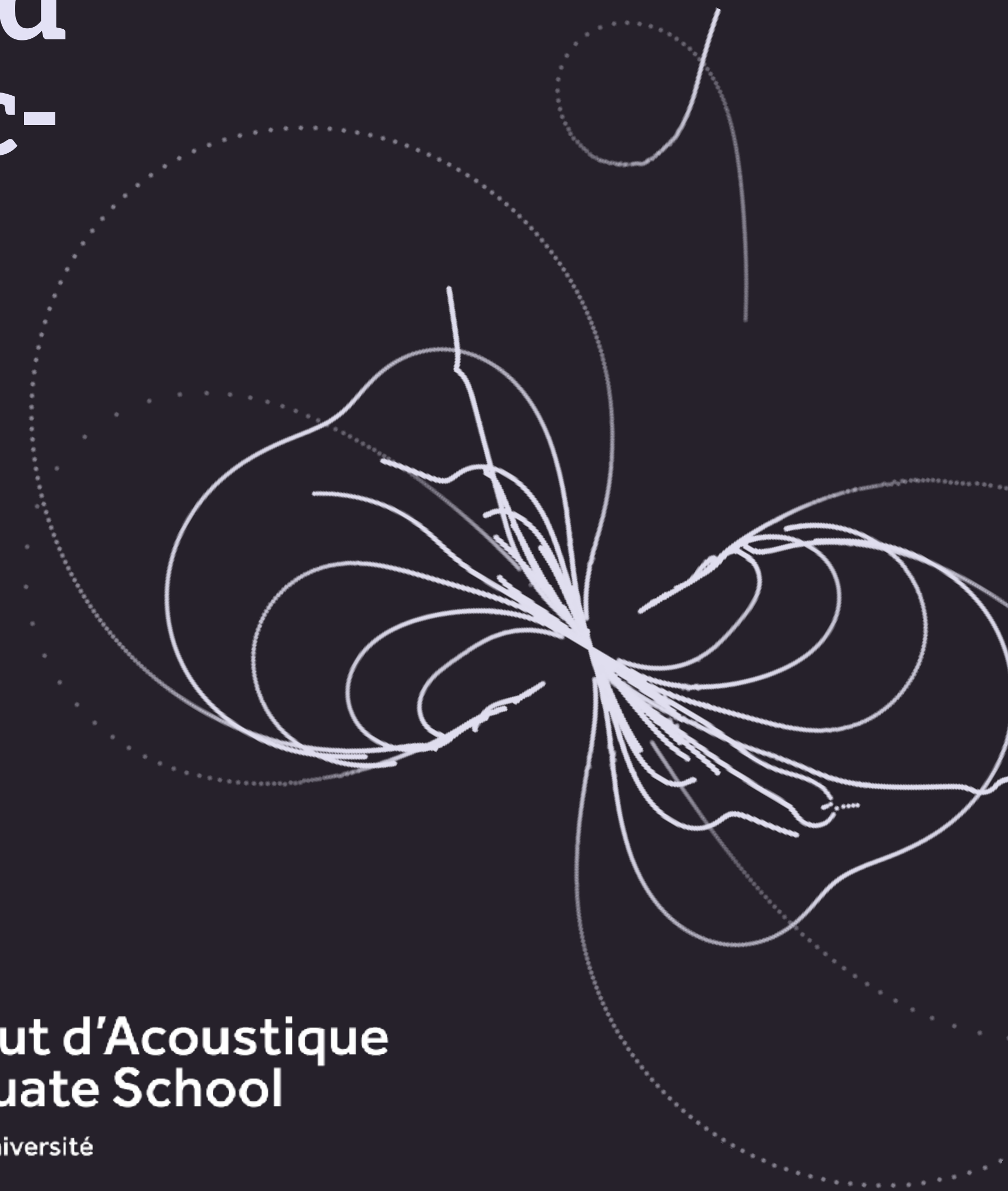
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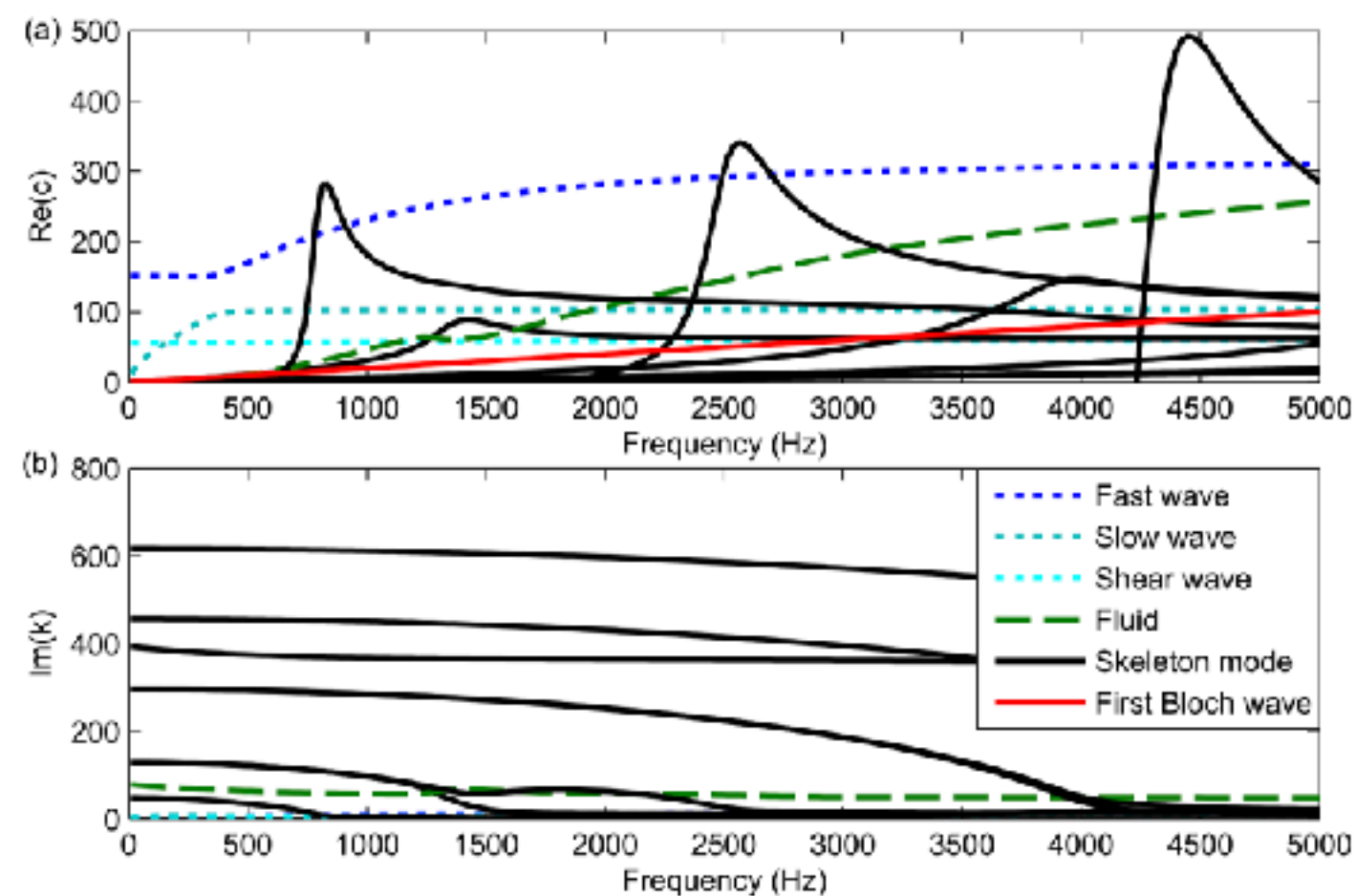
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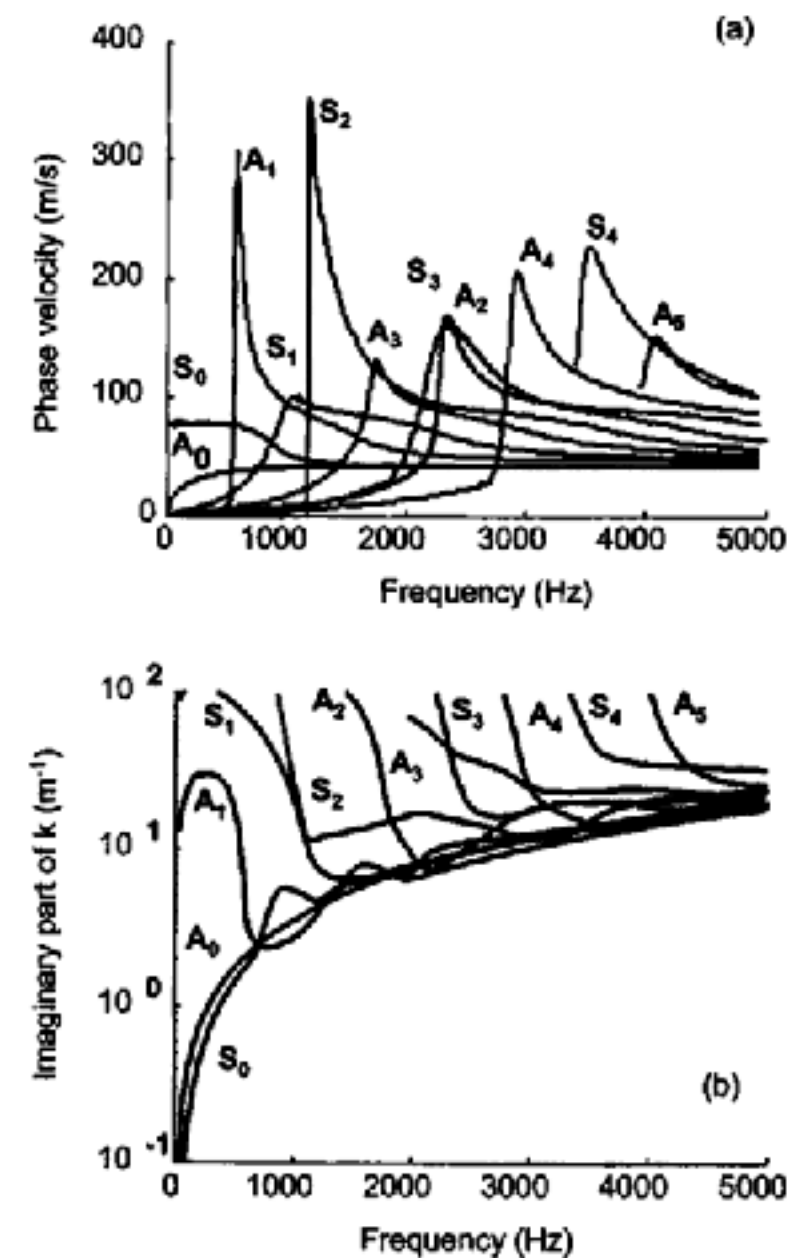


Motivations

- Scarce studies on dispersion analysis of poroelastic media in acoustics
- Computation of the dispersion diagrams of poroelastic based structures
- Existing methods: mostly root-finding



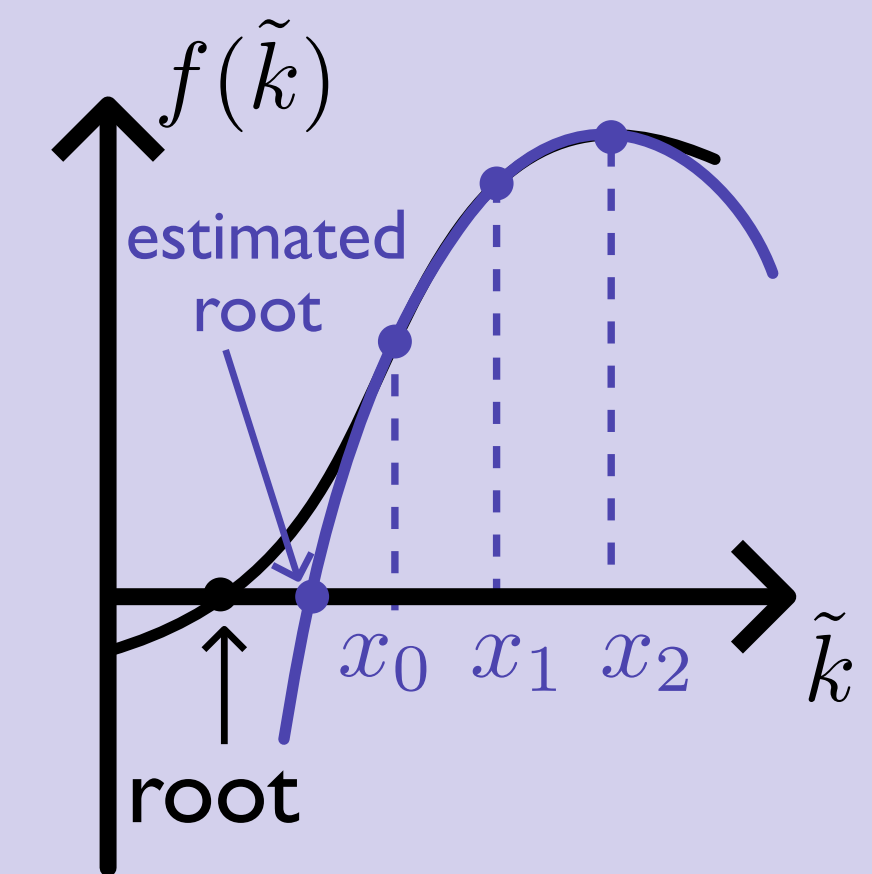
[T.Weisser *et al.*, J. Acoust. Soc. Am. **139** (2), (2016)]



[L. Boeckx *et al.*, J. Appl. Phys., **97**, 094911 (2005)]

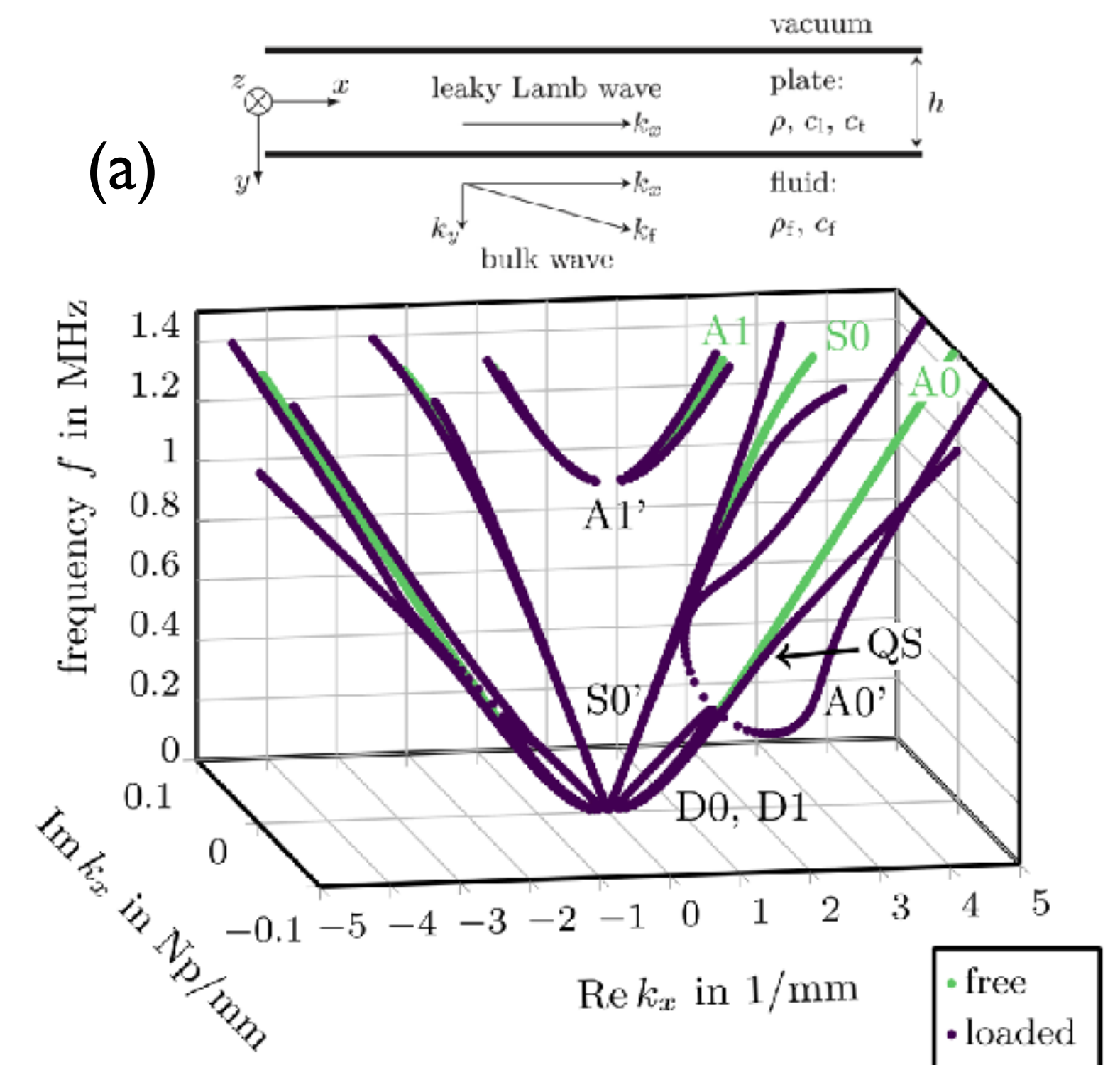
Müller method

- Secant-based method
- Complex roots



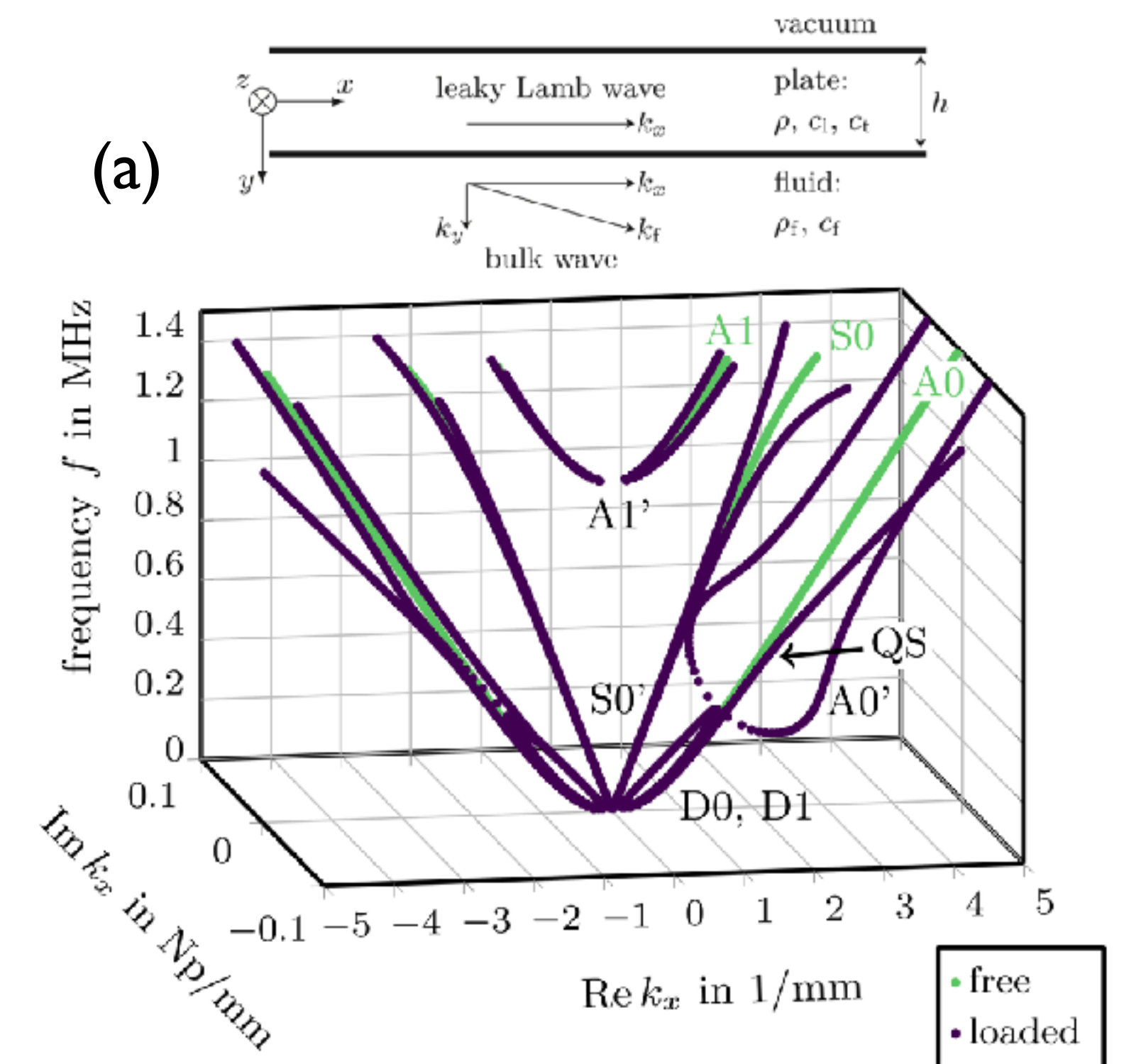
Overview of spectral methods

- Spectral methods: class of numerical methods
- SCM is used widely for dispersion problems involving **elastic materials**:
 - Lamb waves [V. Pagneux et al., *J. Acoust. Soc. Am.* **110**, 1307–1314 (2001)]
 - Anisotropic multilayer elastic media [F. Quintanilla et al., *J. Acoust. Soc. Am.* **137**, 1180–1194 (2015)]
 - Fluid-coupled elastic layer:
 - Mapped discretized surrounding fluid [E. Georgiades et al., *J. Acoust. Soc. Am.* **152**, 1487–1497 (2022)]
 - Change of variable (a) and solving a generalized eigenvalue problem (GEP) [D. Kiefer et al., *J. Acoust. Soc. Am.*, **145**, 3341 (2019)]



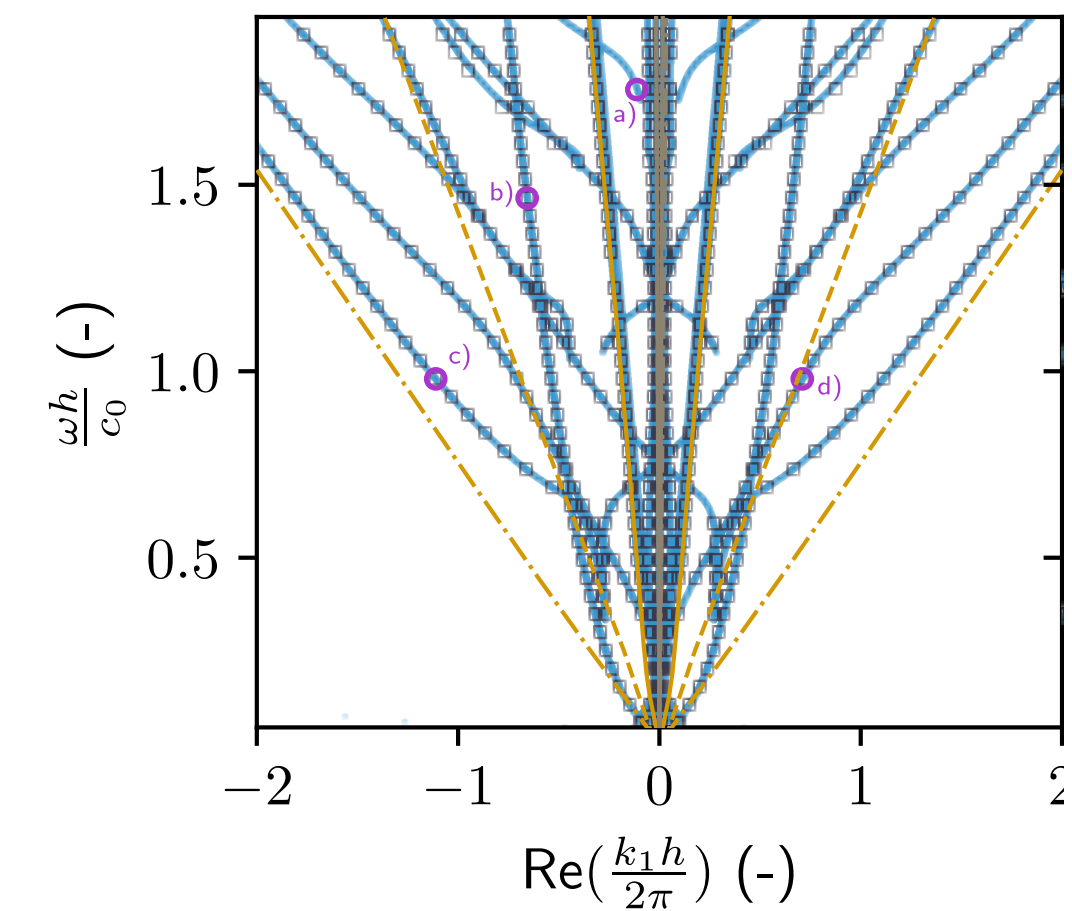
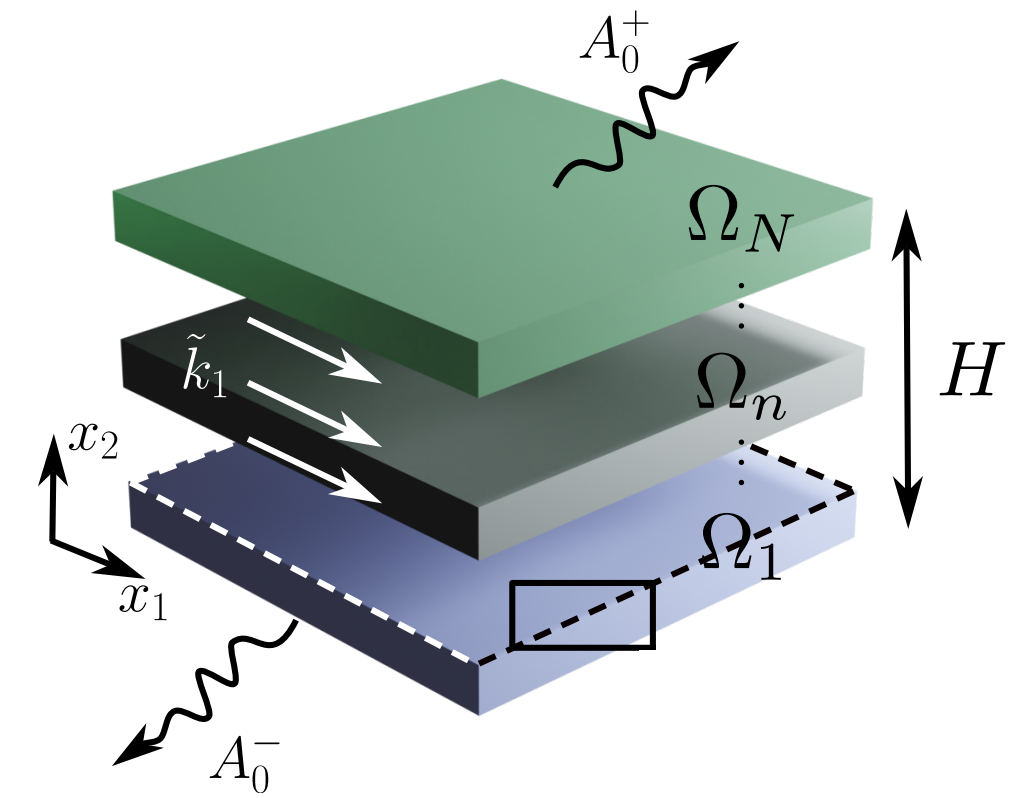
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Outline

- Method description
 - Spectral collocation
 - Multilayer structure
 - Solution of the eigenvalue problem
- Results for a bilayer structure
 - Dispersion diagram & mode shapes
 - Experimental comparisons
- Conclusion & Outlooks



Spectral collocation method: generalities

- Set of fields $\mathbf{s} = \mathbf{s}(x_2)e^{ik_1x_1}e^{-i\omega t}$
- Expansion of the fields in polynomial form $s(x_2) \approx \sum_{n=0}^{\infty} \alpha_n \psi_n$ Basis functions
- Chebyshev nodes distribution
- 1D Grid along an axis $x_m = \cos\left(\frac{(2m-1)\pi}{2M}\right), m = 0 \dots M$

Residue equation for each node

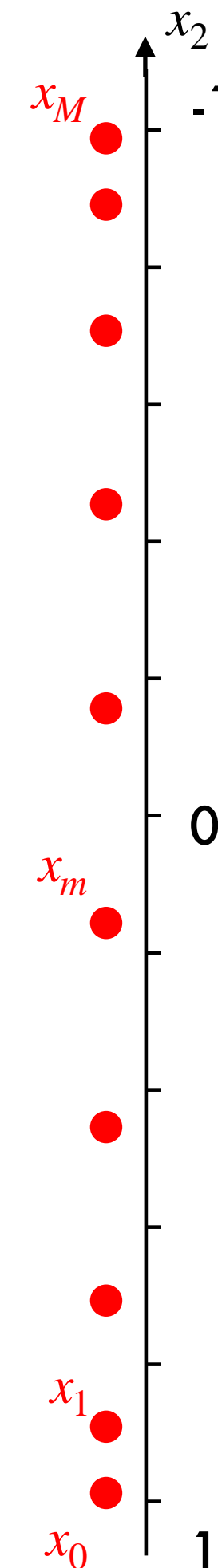
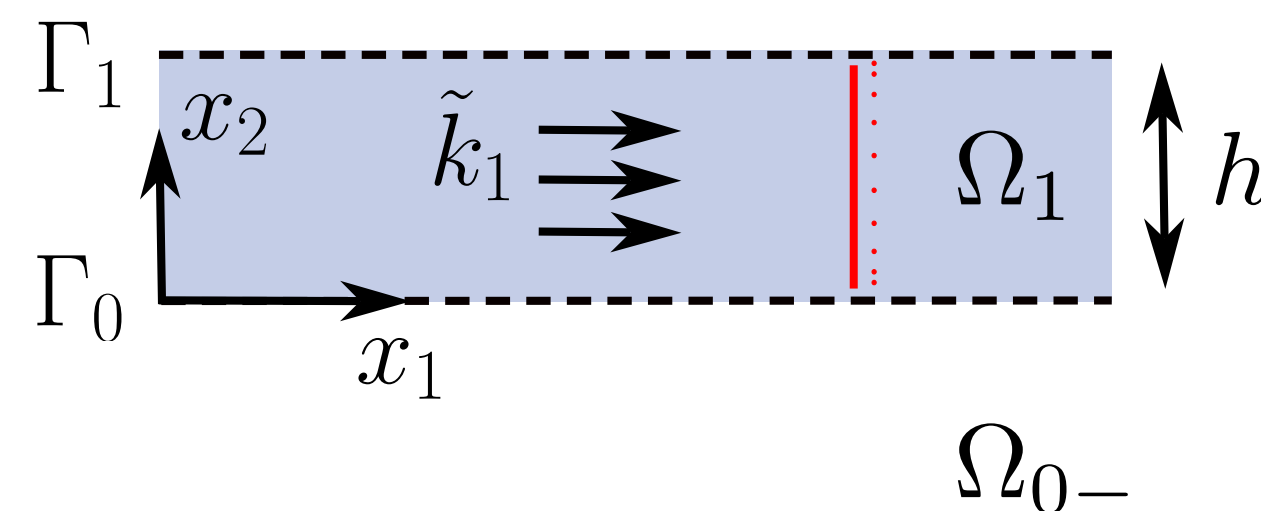
$$\sum_{n=1}^{N-1} \alpha_n \mathcal{L}[T_n](x_m) = 0$$

Chebyshev polynomials

- Notation for the derivatives of Chebyshev polynomials

$$\sum_n \alpha T'(x_m) \rightarrow \mathbf{T}_2$$

$$\sum_n \alpha T''(x_m) \rightarrow \mathbf{T}_{22}$$



- Linear operator \mathcal{L} of the motion equations acting on a layer
- The boundary conditions Γ_0, Γ_1 are applied on the edges x_0, x_M of the grid
- Introduction of differentiation matrices

$$\frac{\partial s}{\partial x_2} \approx \left(\frac{2}{h}\right) \mathbf{D}_2^M \mathbf{s},$$

$$\frac{\partial^2 s}{\partial x_2^2} \approx \left(\frac{2}{h}\right)^2 \mathbf{D}_{22}^M \mathbf{s},$$

$$\mathbf{s} = (s_0, \dots, s_M)$$

[J.A. Weideman, S.C. Reddy, ACM Trans Math Softw, 26, 4, 465-519 (2000)]

[L. Trefethen, Spectral methods in MATLAB, SIAM (2000)]

Case of the SCM with a poroelastic layer

- Discretization of the (u_s, p) formulation equations

$$\begin{aligned} \nabla \cdot \hat{\boldsymbol{\sigma}}^s + \tilde{\rho} \omega^2 \mathbf{u}^s + \tilde{\gamma} \nabla p &= 0, \\ \frac{\nabla^2 p}{\tilde{\rho}_{22} \omega^2} - \frac{\tilde{\gamma}}{\phi^2} \nabla \cdot \mathbf{u}^s + \frac{1}{\tilde{R}} p &= 0. \end{aligned}$$

[N. Atalla et al., J. Acoust. Soc. Am. **104**, 3 (1998)]

- 3 set of unknowns instead of 4 with the (u_s, u_f) formulation

- Coupling at the interfaces

[P. Debergue et al., J. Acoust. Soc. Am. **106**, 2383–2390 (1999)]

- Fluid-PEM interfaces in the interface Γ_0
- Γ_1 , relation of the fields u_1^s, u_2^s, p with the fields s_2 in α_2 using the appropriate interface conditions

- Notation used

$$\hat{P} = \hat{A} + 2N_s; \quad \hat{A} = \tilde{A} - \frac{\tilde{Q}^2}{\tilde{R}}; \quad \tilde{\rho} = \rho_{11} - \frac{\tilde{\rho}_{12}^2}{\tilde{\rho}_{22}};$$

$$\tilde{\gamma} = \phi \left(\frac{\tilde{\rho}_{12}}{\tilde{\rho}_{22}} - \frac{\tilde{Q}}{\tilde{R}} \right); \quad \hat{\beta} = 1 + \frac{\tilde{\rho}_{12}}{\tilde{\rho}_{22}}$$

$$\mathbf{K} \mathbf{S} = \begin{pmatrix} \Gamma_0^- & \Gamma_0^+ & 0 & & & & \\ 0 & \alpha_1 & 0 & & & & \\ 0 & \Gamma_1^- & \Gamma_1^+ & 0 & & & \\ & 0 & \alpha_2 & 0 & & & \\ & & \vdots & \ddots & \ddots & & \\ & & & 0 & \alpha_N & 0 & \\ & & & 0 & \Gamma_N^- & \Gamma_N^+ & \end{pmatrix} \begin{pmatrix} A_{0-} \\ \mathbf{s}^{(1)} \\ \mathbf{s}^{(2)} \\ \vdots \\ \mathbf{s}^{(N)} \\ A_{0+} \end{pmatrix} = \mathbf{0}.$$

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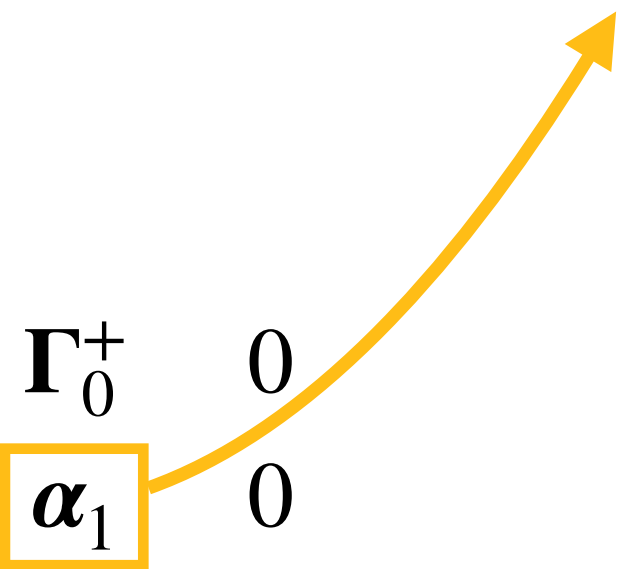
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$$\boldsymbol{\alpha}_1 = \begin{pmatrix} N_s T_{22} + (\omega^2 \tilde{\rho} - \hat{P} k_1^2) \mathbf{T} & (\hat{P} - N_s) i k_1 T_2 & i \tilde{\gamma} k_1 \mathbf{T} \\ (\hat{P} - N_s) i k_1 T_2 & \hat{P} T_{22} + (\omega^2 \tilde{\rho} - N_s k_1^2) \mathbf{T} & \tilde{\gamma} T_2 \\ -i k_1 \tilde{\gamma} / \phi^2 \mathbf{T} & -\tilde{\gamma} / \phi^2 T_2 & T_{22} / \tilde{\rho}_{22} \omega^2 - \left(k_1^2 / \tilde{\rho}_{22} \omega^2 + \frac{1}{\tilde{R}} \right) \mathbf{T} \end{pmatrix}$$

$$\mathbf{K} \mathbf{S} = \begin{pmatrix} \Gamma_0^- & \Gamma_0^+ & 0 & & & \\ 0 & \alpha_1 & 0 & & & \\ 0 & \Gamma_1^- & \Gamma_1^+ & 0 & & \\ & 0 & \alpha_2 & 0 & & \\ & & \vdots & \ddots & \ddots & \\ & & & 0 & \alpha_N & 0 \\ & & & 0 & \Gamma_N^- & \Gamma_N^+ \end{pmatrix} \begin{pmatrix} A_{0-} \\ \mathbf{s}^{(1)} \\ \mathbf{s}^{(2)} \\ \vdots \\ \mathbf{s}^{(N)} \\ A_{0+} \end{pmatrix} = \mathbf{0}.$$


Linearization of the generalized eigenvalue problem

The matrix system previously obtained is

$$\mathbf{K}\mathbf{S} = \mathbf{0}, \quad \text{with } \mathbf{S} = (A_{0-}, s_0, \dots, s_n, \dots, s_N, A_{0+}).$$

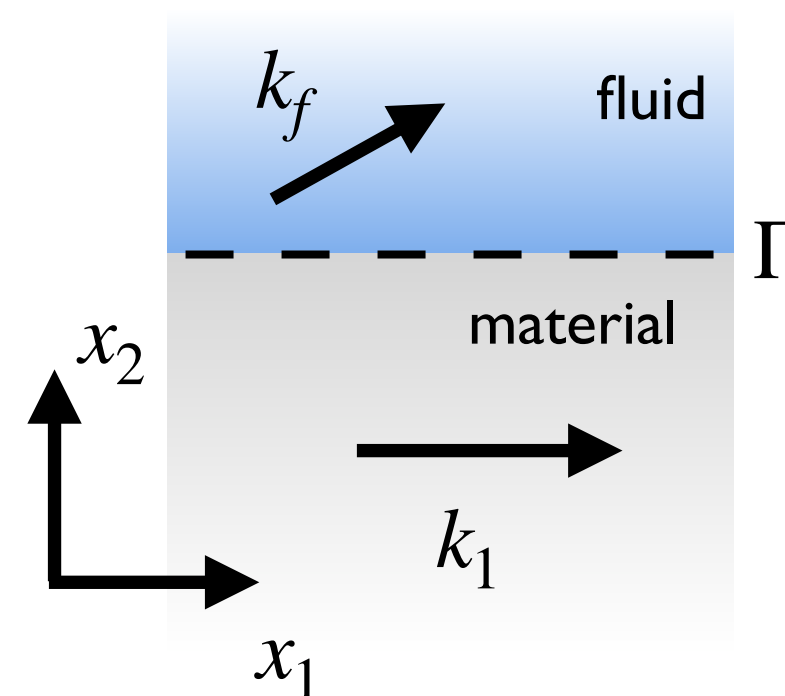
It can be rewritten as

$$\left(k_1^2 \mathbf{K}_2 + k_1 \mathbf{K}_1 + \mathbf{K}_0 + ik_2^{(f)} \mathbf{K}'_1 \right) \mathbf{S} = \mathbf{0}$$

$$\text{with } k_2^{(f)} = \sqrt{\left(\frac{\omega}{c_f}\right)^2 - k_1^2},$$

which is a non-linear GEP. Let

$$k_1 = k^{(f)} \frac{\gamma + \gamma^{-1}}{2}, \quad k_2 = k^{(f)} \frac{\gamma - \gamma^{-1}}{2i}.$$



[D. Kiefer et al., *J. Acoust. Soc. Am.*, **145**, 3341 (2019)]

[A. Hood, *Localizing the eigenvalues of matrix-valued functions: analysis and applications*, Cornell University (2017)]

By using companion linearization,

$$(\mathbf{A} - \gamma \mathbf{B}) \mathbf{S}' = \mathbf{0}$$

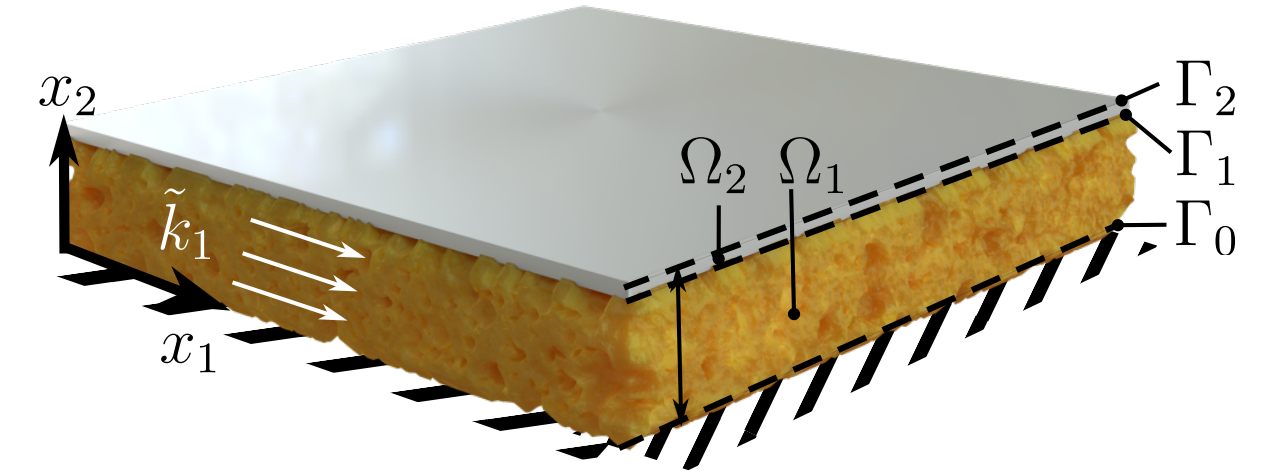
eigenvalues \nearrow eigenvectors \nearrow

$$\mathbf{S}' = \begin{pmatrix} \gamma^3 \mathbf{S} \\ \gamma^2 \mathbf{S} \\ \gamma \mathbf{S} \\ \mathbf{S} \end{pmatrix}$$

GEP solvable with traditional eigenvalue solvers

Dispersion relation of the structure

- Melamine foam, rigidly-backed with an aluminium plate on top
- Coupling between the elastic plate and the melamine at Γ_1



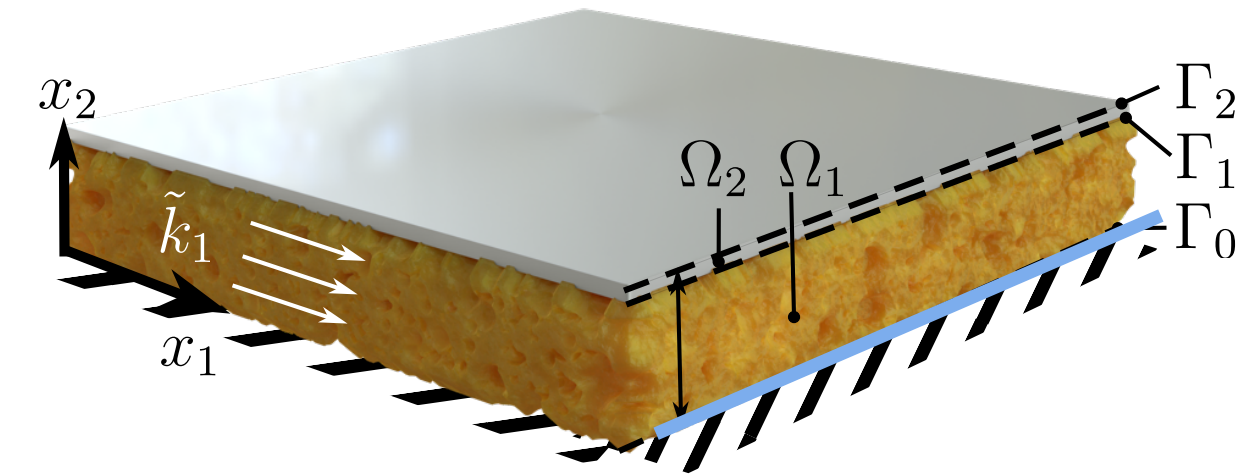
$$\begin{pmatrix} \Gamma_0 & 0 & 0 \\ \alpha_1 & 0 & 0 \\ \Gamma_1^- & \Gamma_1^+ & 0 \\ 0 & \alpha_2 & 0 \\ 0 & \Gamma_2^- & \Gamma_2^+ \end{pmatrix} \begin{pmatrix} \mathbf{s}^{(p)} \\ \mathbf{s}^{(e)} \\ A_{0+} \end{pmatrix} = \mathbf{0}$$

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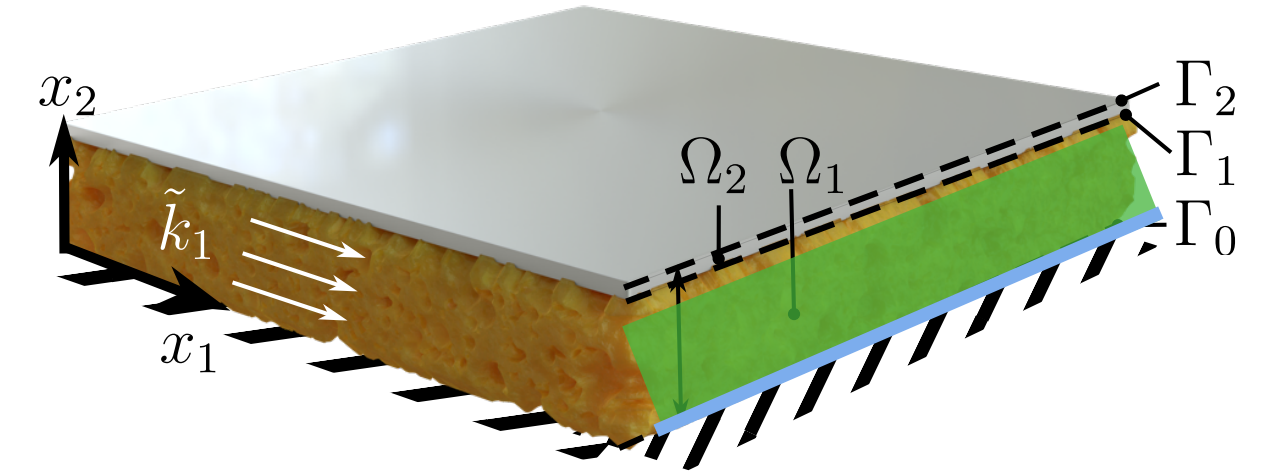
Rigid-backing BC

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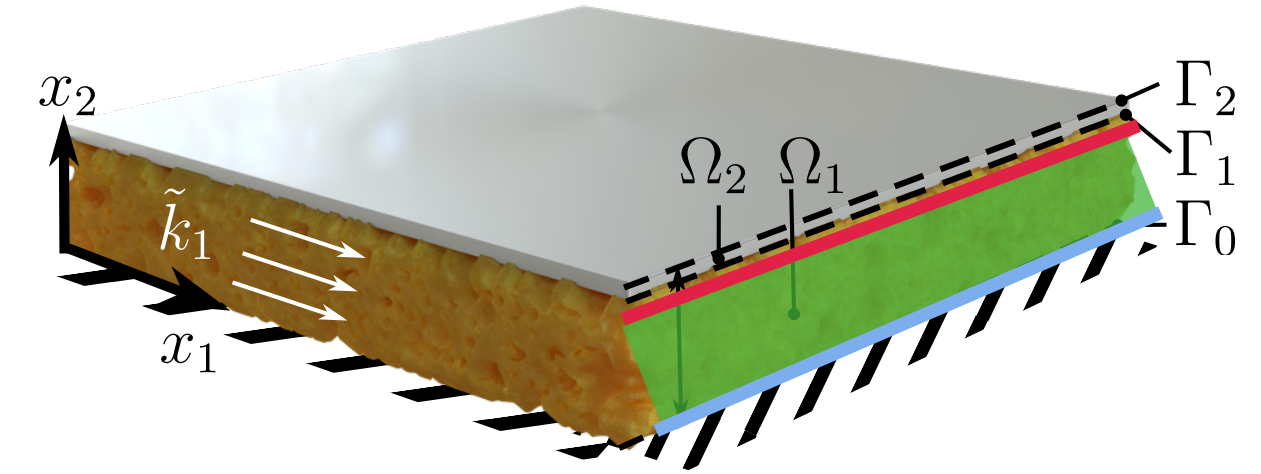
Rigid-backing BC

Biot model

$$\begin{pmatrix} \Gamma_0 & 0 & 0 \\ \alpha_1 & 0 & 0 \\ \Gamma_1^- & \Gamma_1^+ & 0 \\ 0 & \alpha_2 & 0 \\ 0 & \Gamma_2^- & \Gamma_2^+ \end{pmatrix} \begin{pmatrix} \mathbf{s}^{(p)} \\ \mathbf{s}^{(e)} \\ A_{0+} \end{pmatrix} = \mathbf{0}$$

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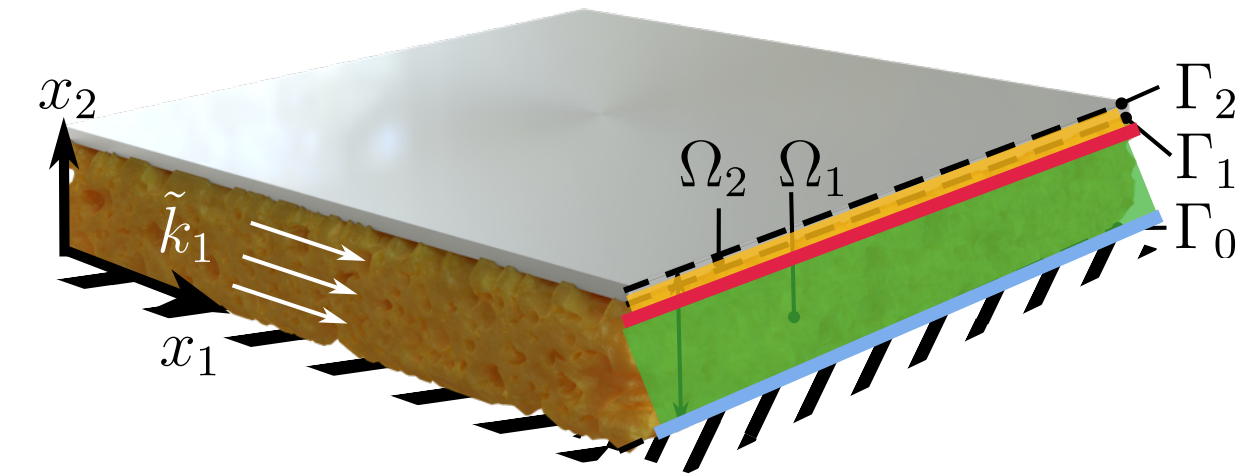


Rigid-backing BC

$$\begin{array}{l}
 \text{Biot model} \\
 \text{IC Elastic-PEM}
 \end{array}
 \begin{pmatrix}
 \Gamma_0 & 0 & 0 \\
 \alpha_1 & 0 & 0 \\
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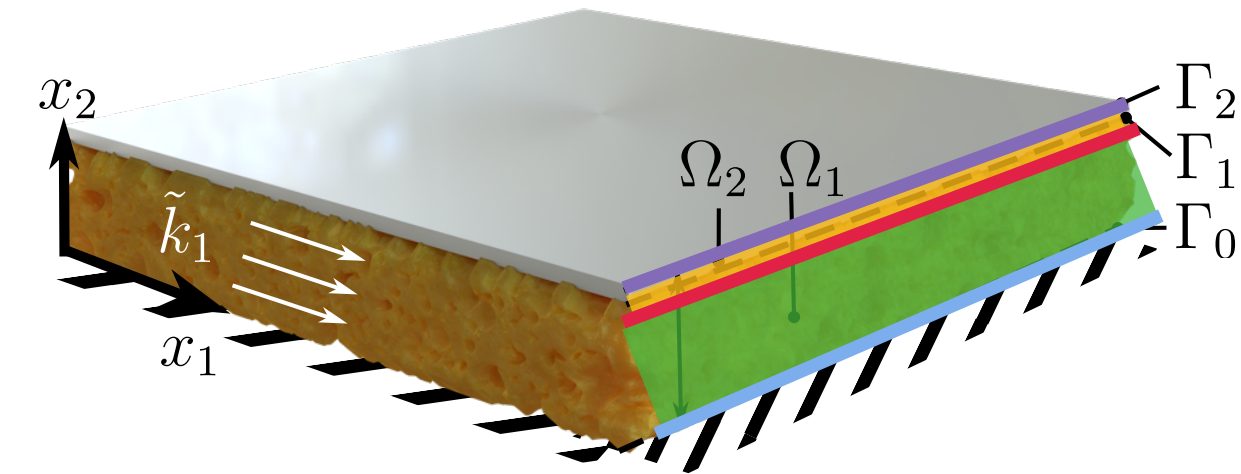


Rigid-backing BC

$$\begin{array}{l}
 \text{Biot model} \\
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 \text{Discretized} \\
 \text{elasticity} \\
 \text{equation}
 \end{array}
 \begin{pmatrix}
 \Gamma_0 & 0 & 0 \\
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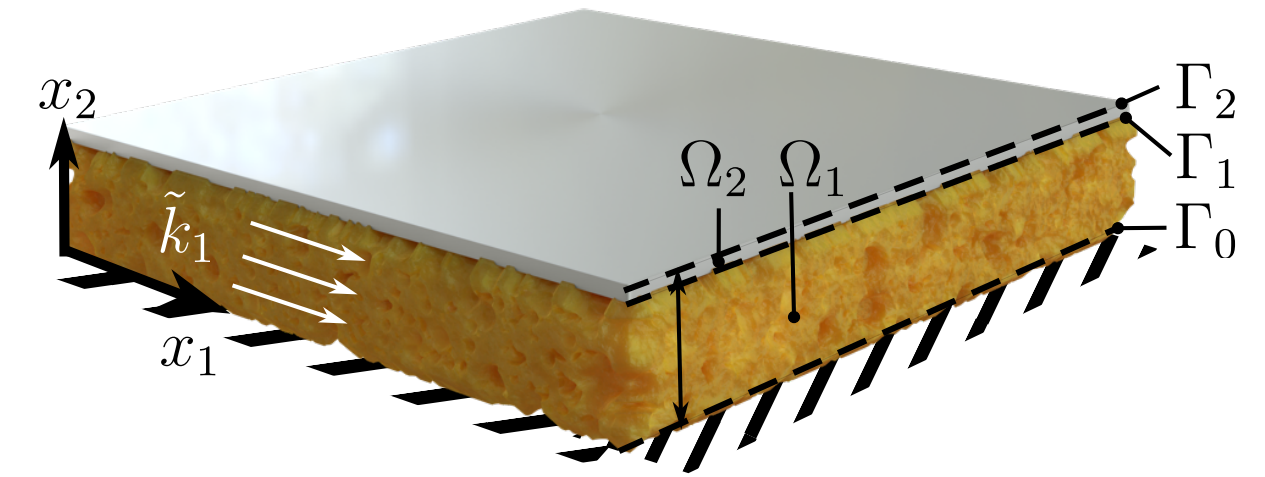
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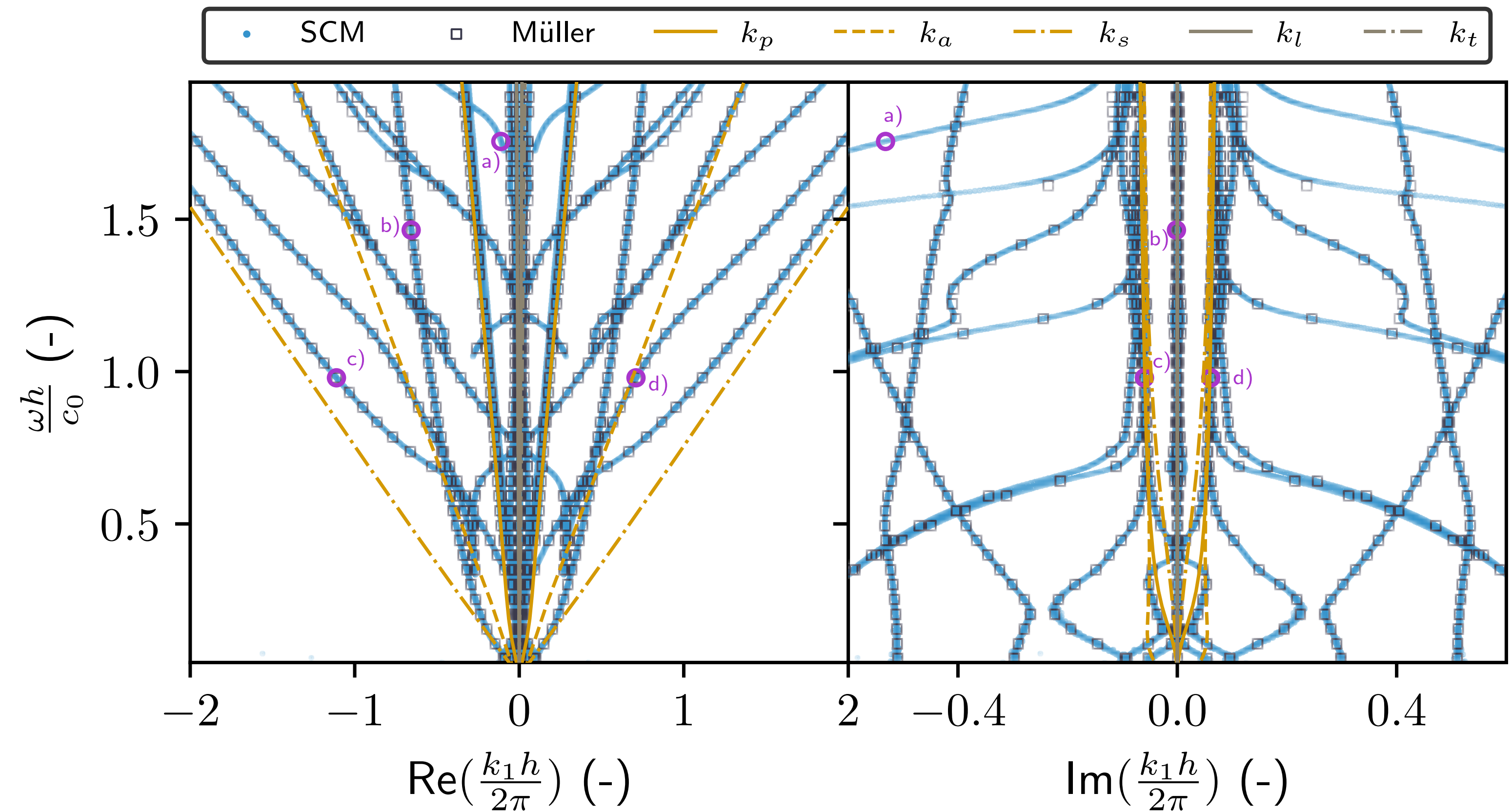
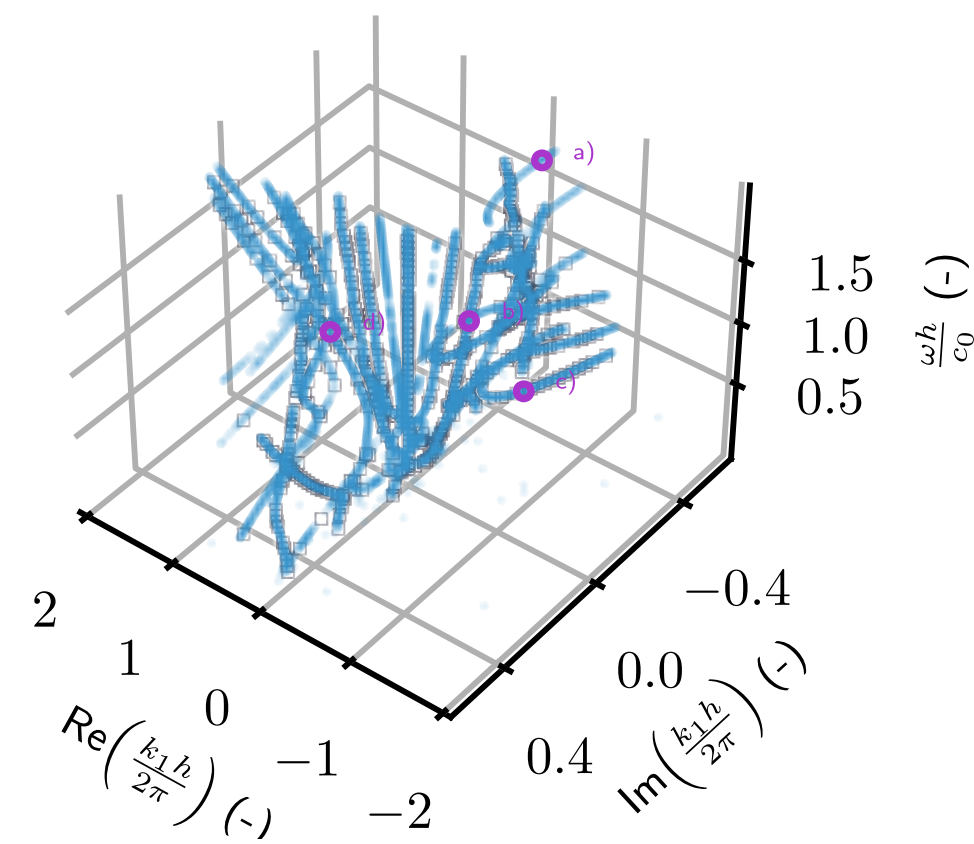
Elastic-fluid coupling

Dispersion relation of the structure

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$$\begin{pmatrix} \Gamma_0 & 0 & 0 \\ \alpha_1 & 0 & 0 \\ \Gamma_1^- & \Gamma_1^+ & 0 \\ 0 & \alpha_2 & 0 \\ 0 & \Gamma_2^- & \Gamma_2^+ \end{pmatrix} \begin{pmatrix} \mathbf{s}^{(p)} \\ \mathbf{s}^{(e)} \\ A_{0+} \end{pmatrix} = \mathbf{0}$$



Retrieving the mode shapes of the system

- From $(\mathbf{A} - \gamma\mathbf{B}) \mathbf{S}' = \mathbf{0}$, for a given $\tilde{k}_1 \rightarrow s(x_j)$
 - Expansion coefficients $\alpha[s] = \mathbf{T}_m^{-1}(x_j)s(x_j)$
 - Reinterpolated fields $s(x_2) = \alpha[s]T_m(x_2)$

- u_1^s, u_2^s, p for the PEM, and u_1^s, u_2^s for the elastic layer

- Fluid displacement computed using $\mathbf{u}_f = \frac{\phi}{\tilde{\rho}_{22}\omega^2} \nabla p - \frac{\tilde{\rho}_{12}}{\tilde{\rho}_{22}} \mathbf{u}_s$

- Calculation of the Umov-Poynting vectors in the PEM $\mathbf{P}_t = -\frac{1}{2} \boldsymbol{\sigma} \mathbf{v}^*$

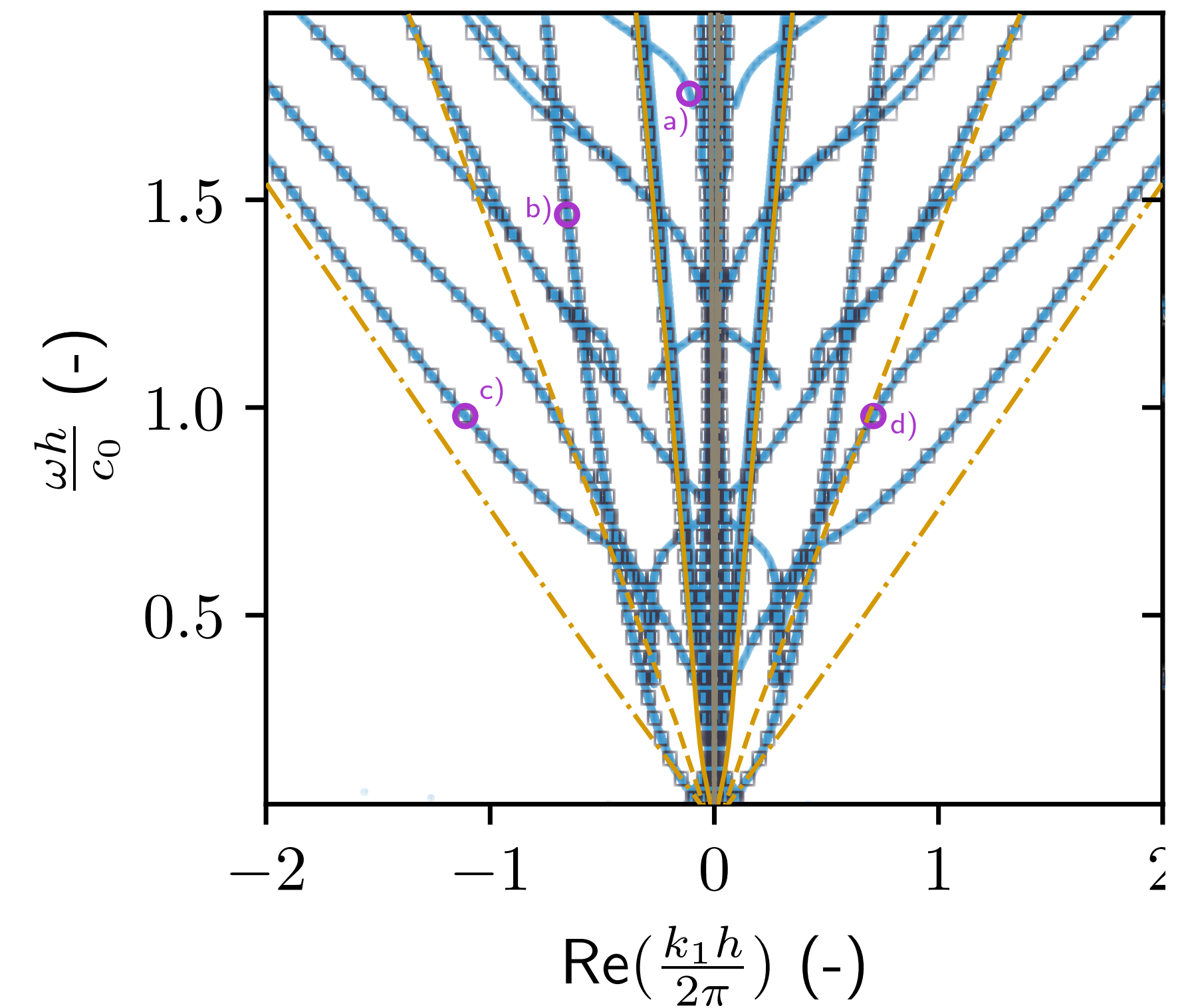
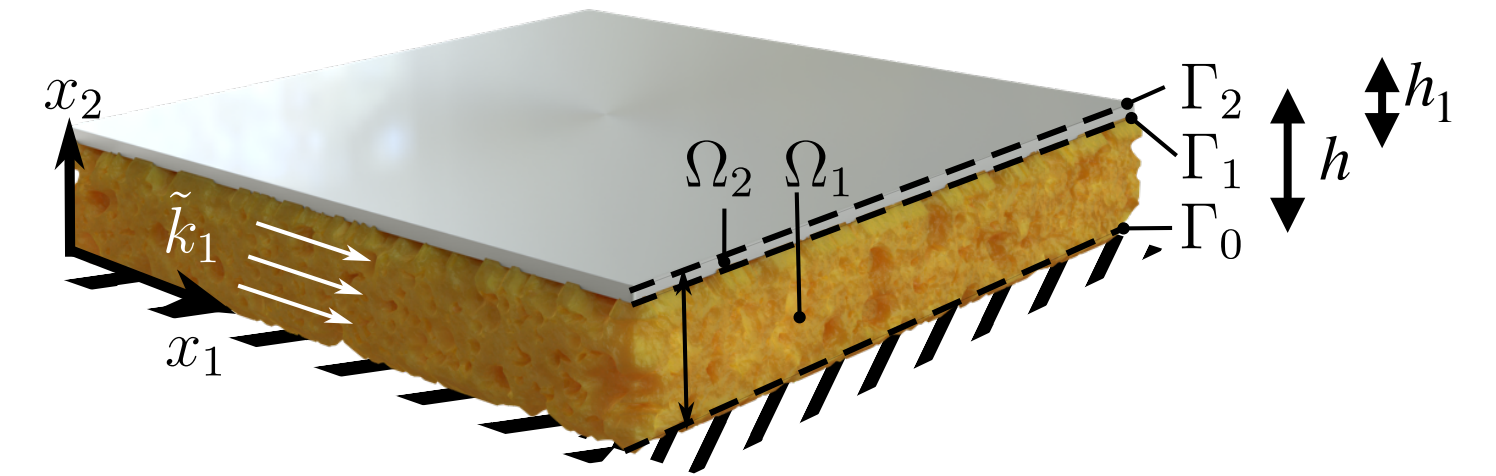
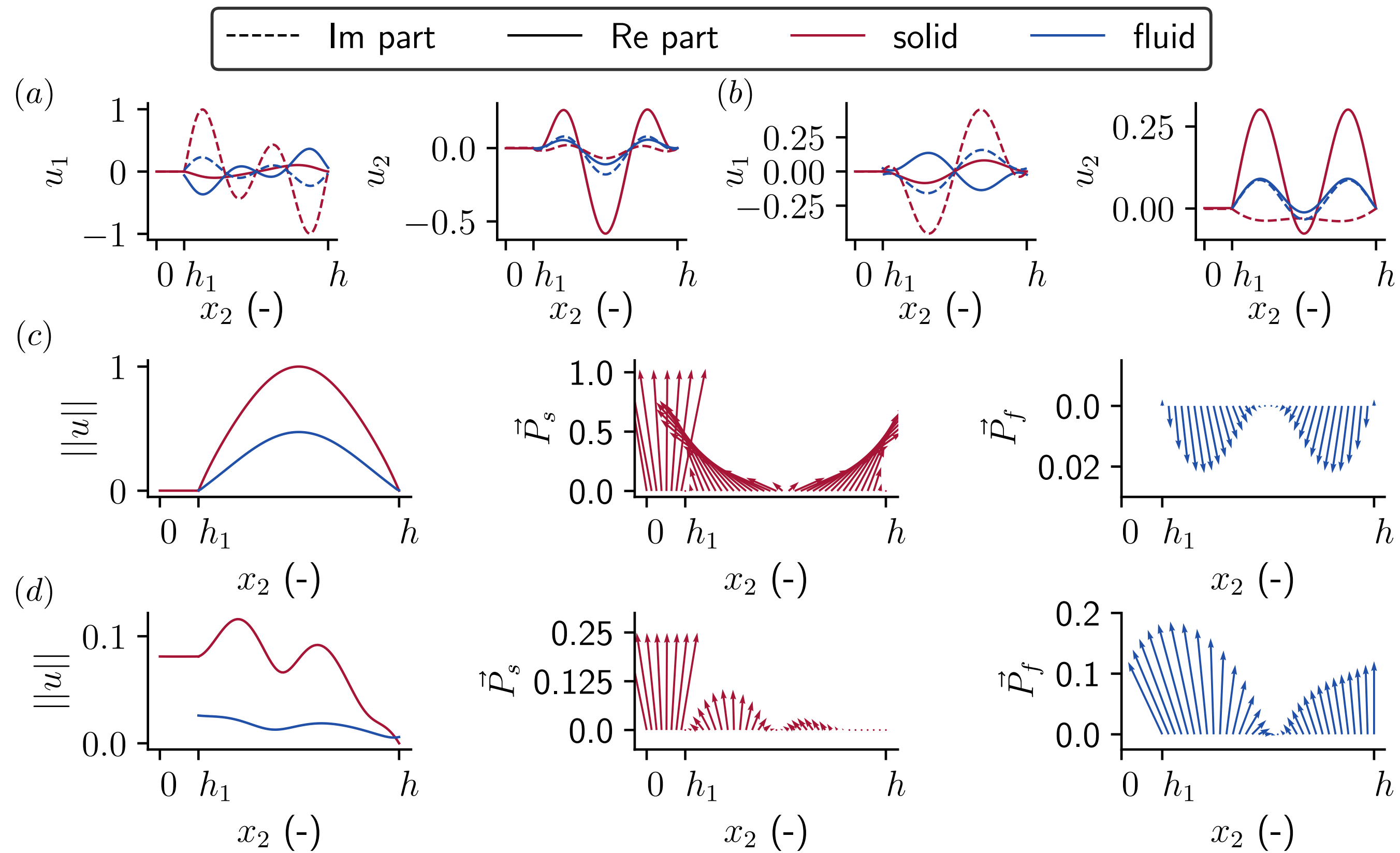
[J. M. Carcione, Wave fields in real media, Elsevier (2007)]

Decoupled solid and fluid phases

$$\begin{cases} P_s = -\frac{1}{2} \boldsymbol{\sigma}_s \mathbf{v}_s^* \\ P_f = -\frac{1}{2} \boldsymbol{\sigma}_f \mathbf{v}_f \end{cases}$$

$$\begin{aligned} \mathbf{v}_s &= -i\omega \mathbf{u}_s & \boldsymbol{\sigma}_s &= \underbrace{\hat{A} \nabla \cdot \mathbf{u}_s \mathbf{I} + 2\tilde{N}_s \boldsymbol{\epsilon}_s}_{\hat{\boldsymbol{\sigma}}_s} - \phi \frac{\tilde{Q}}{\tilde{R}} p \mathbf{I} \\ \mathbf{v}_f &= -i\omega \mathbf{u}_f & \boldsymbol{\sigma}_f &= -\phi p \mathbf{I} \end{aligned}$$

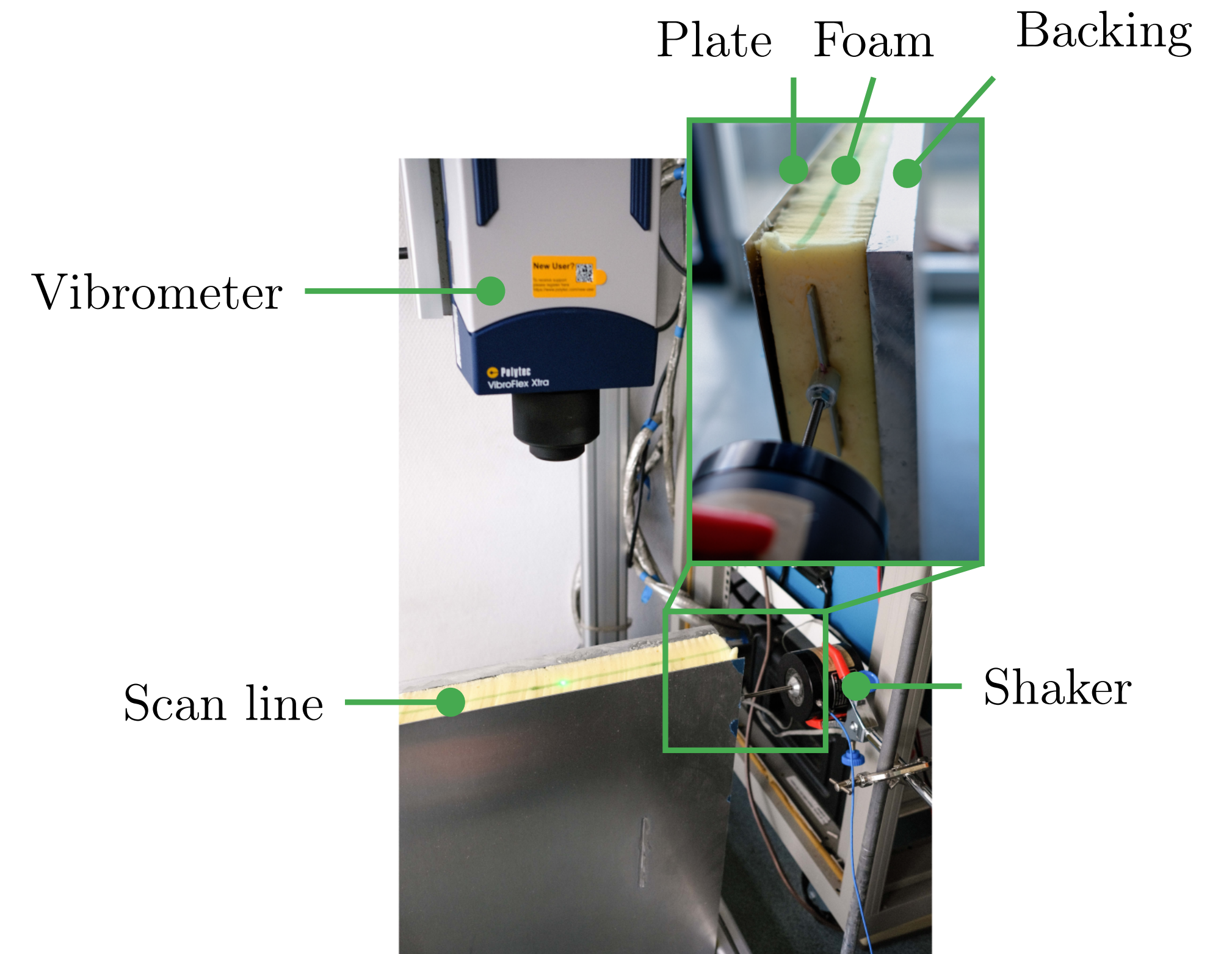
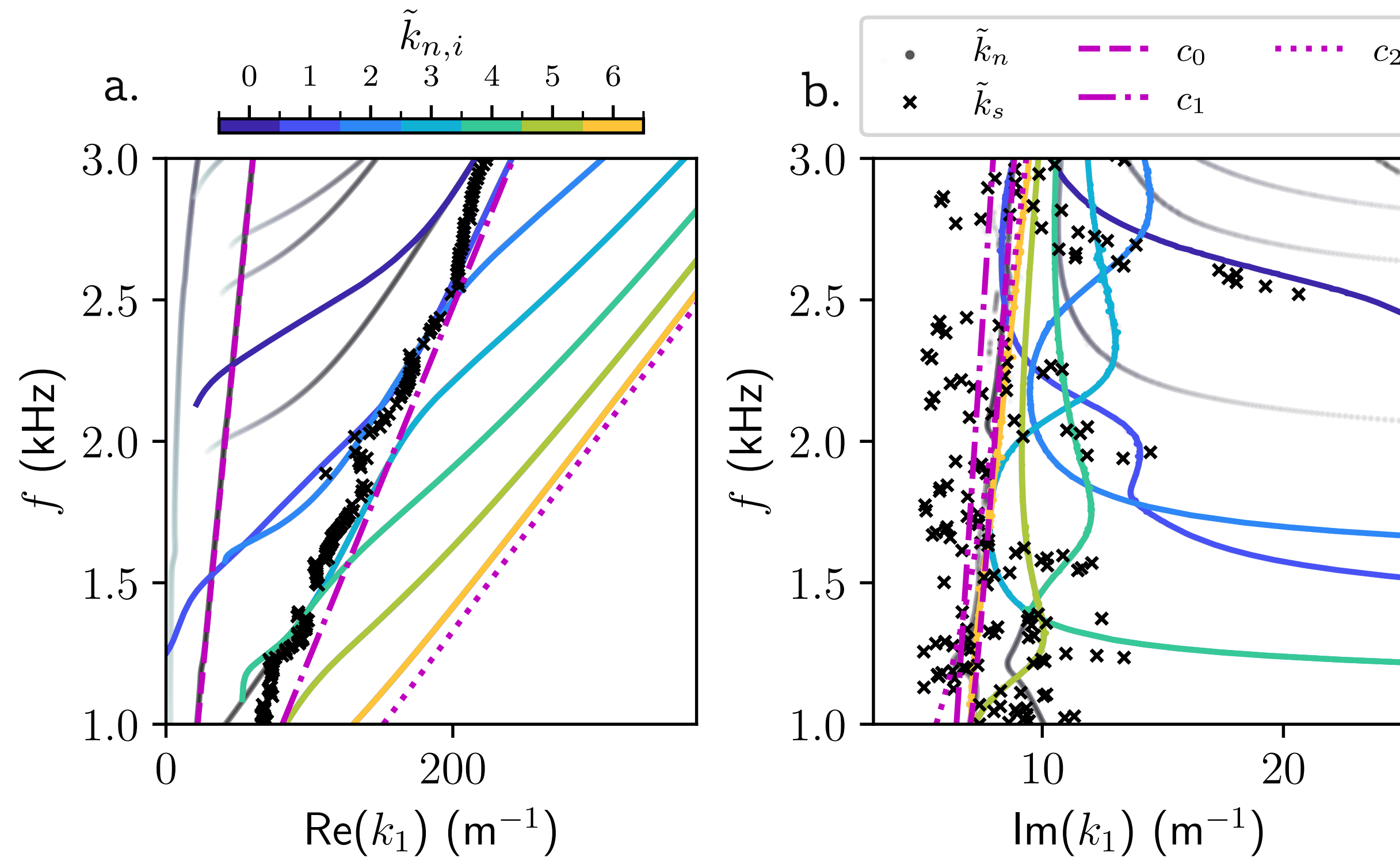
Mode shapes & Umov-Poynting vectors



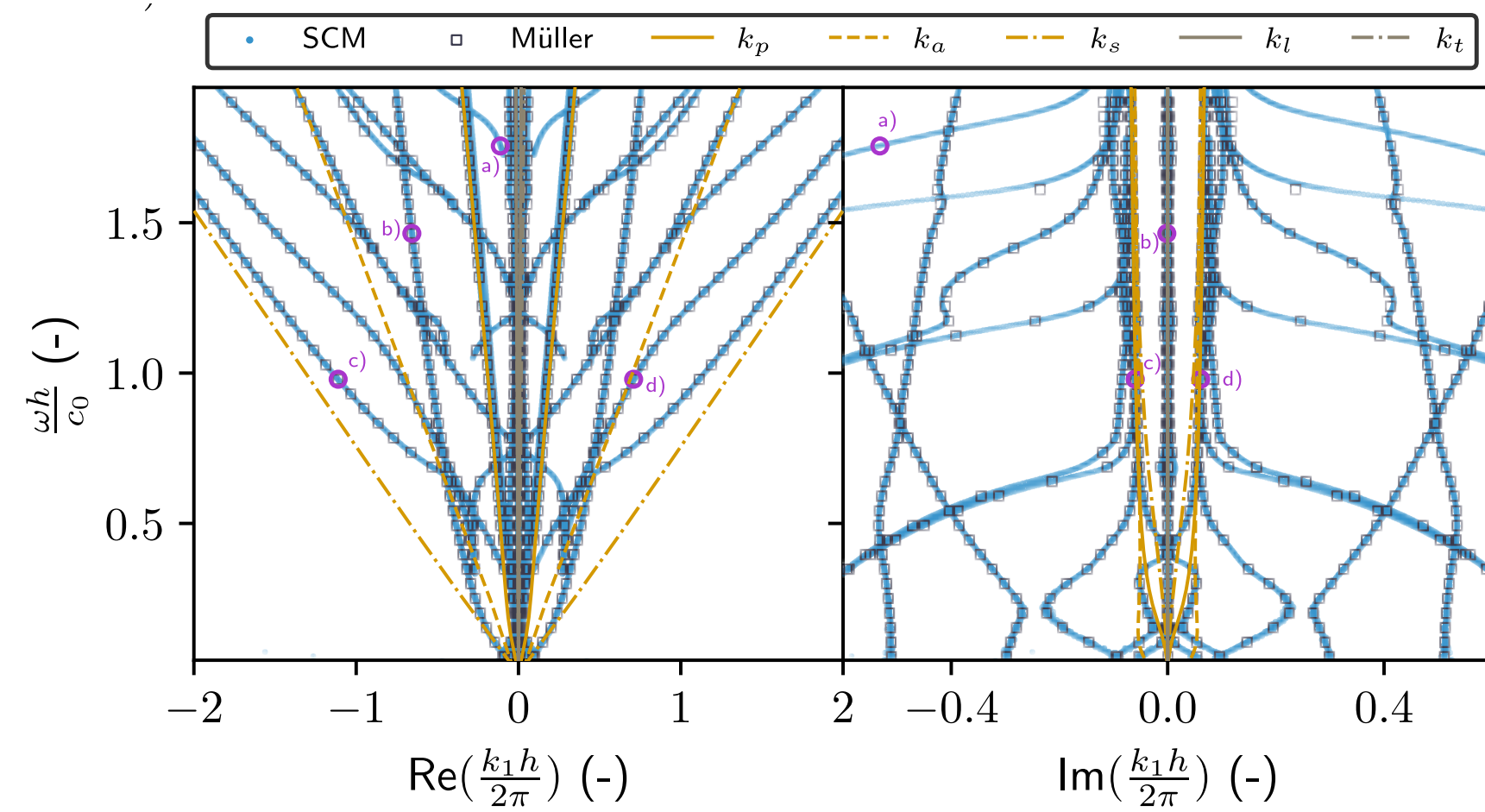
Experimental comparisons

- Experimental configuration, with the same bilayer structure
- Scan measurement of the normal displacement on the sample
- Recovery of complex wavenumbers \tilde{k}_s using the SLaTCoW method

[A. Geslain *et al.* J. Appl. Phys. **120**, 13, p.135107 (2016)]

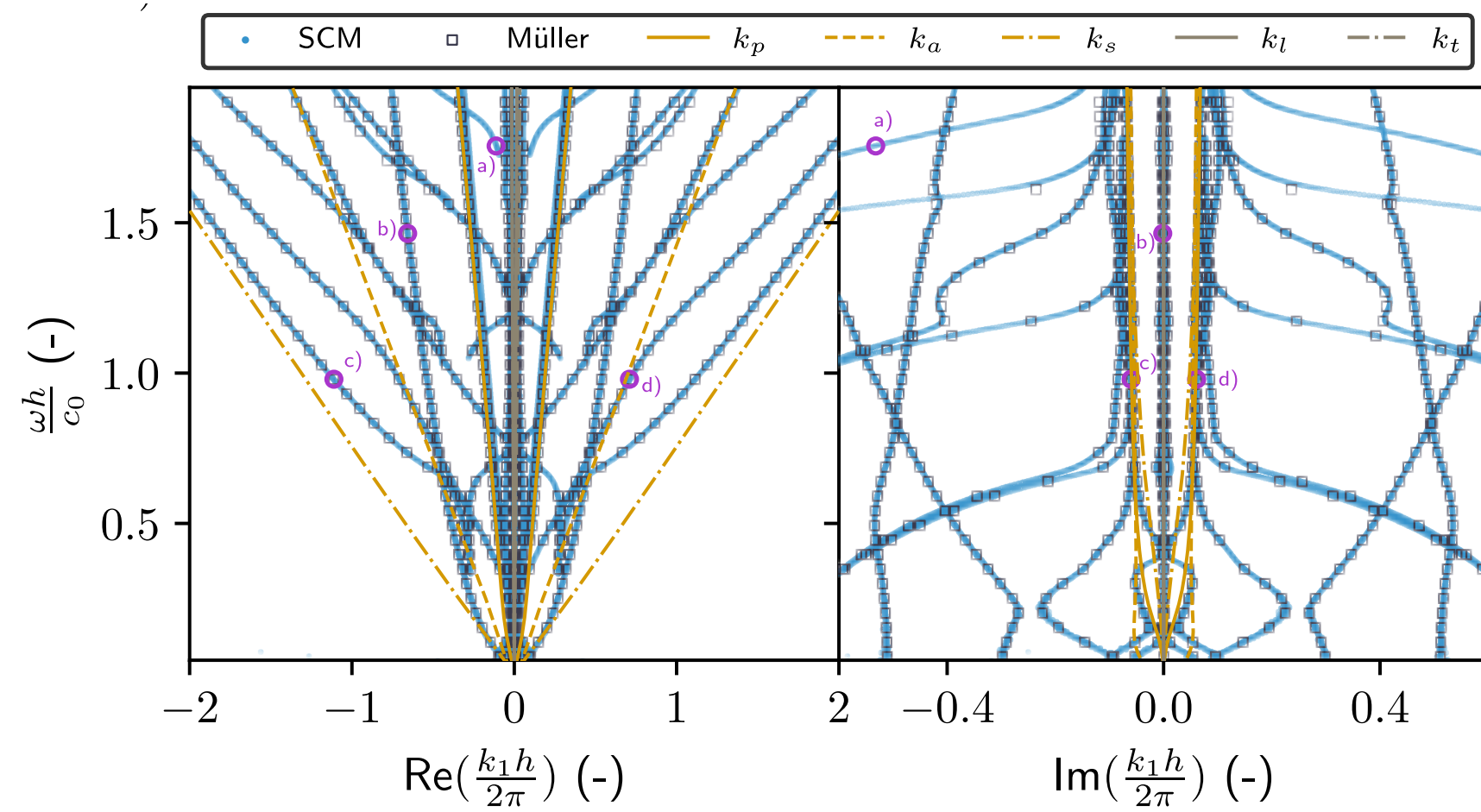


Conclusion & Outlooks



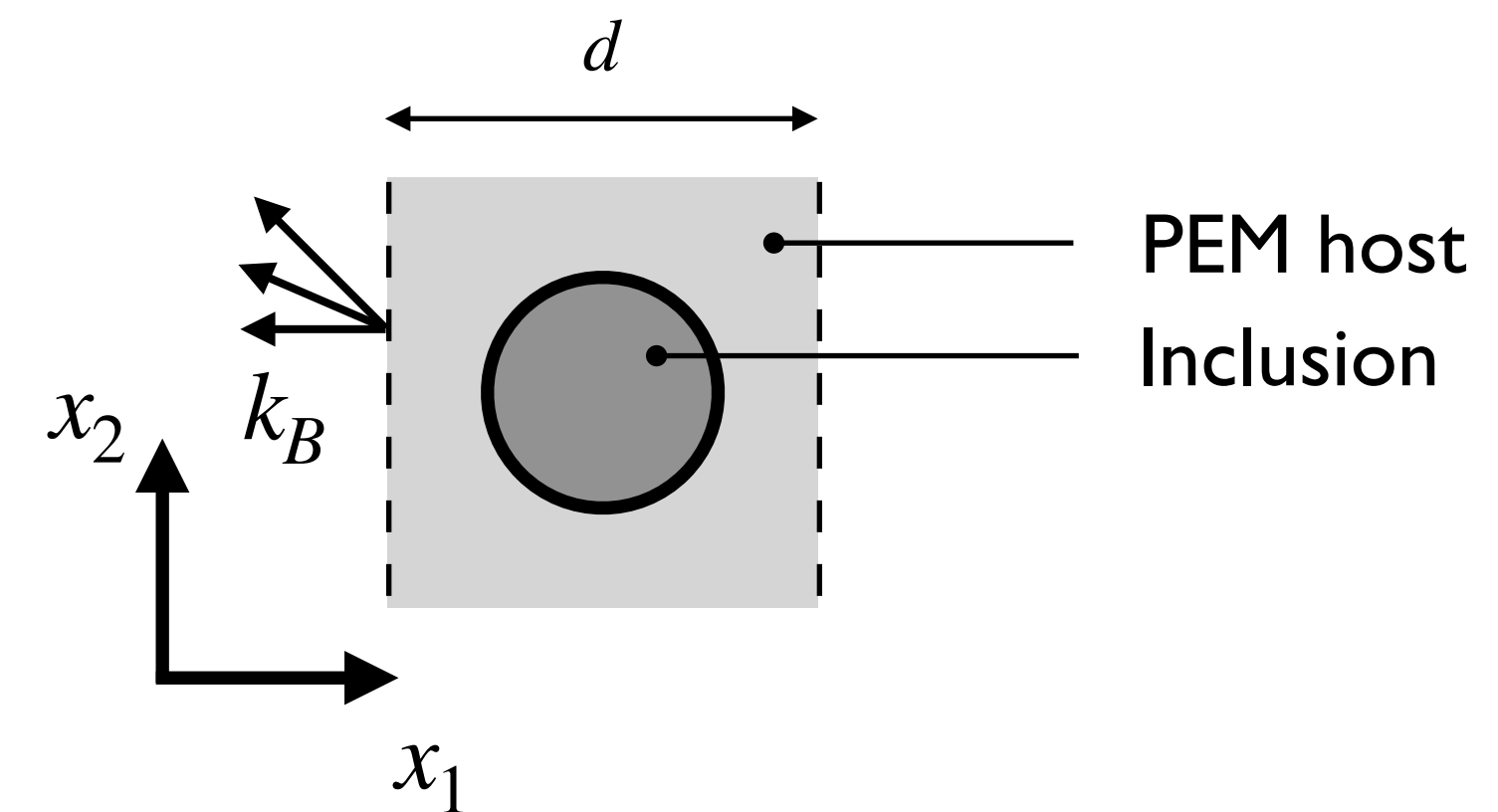
- Numerical method to study guided waves in general multilayer structures
- Fast and accurate computation of dispersion diagrams
- Mode shapes are obtained with no additional computational cost: allows to compute Umov-Poynting vectors
- Results match with the Müller method and experimental results

Conclusion & Outlooks



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- Efficiently sort the different branches of the dispersion diagram
 - Study some modes specifically
 - Sorting of the mode shapes
- Add inclusions in the system to provide periodicity: adaptation of the SCM to study periodic structures



Thank you for your attention !

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